Chapter 5: outline

5.1 introduction

5.2 routing protocols

- link state
- distance vector

5.3 intra-AS routing in the Internet: OSPF

5.4 routing among the ISPs: BGP

5.5 The SDN control plane

5.6 ICMP: The Internet Control Message Protocol

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Distance vector algorithm

Bellman-Ford equation (dynamic programming)

let

$d_x(y)$:= cost of least-cost path from x to y

then

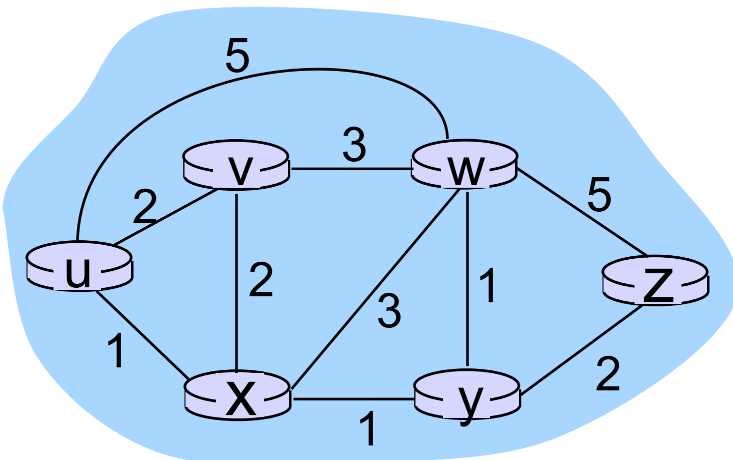
$$d_x(y) = \min_v \{c(x,v) + d_v(y)\}$$

cost from neighbor v to destination y

cost to neighbor v

min taken over all neighbors v of x

Bellman-Ford example



clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$\begin{aligned} d_u(z) = \min \{ & c(u,v) + d_v(z), \\ & c(u,x) + d_x(z), \\ & c(u,w) + d_w(z) \} \\ = \min \{ & 2 + 5, \\ & 1 + 3, \\ & 5 + 3\} = 4 \end{aligned}$$

node achieving minimum is next hop in shortest path, used in forwarding table

Distance vector algorithm

- $D_x(y)$ = estimate of least cost from x to y
  - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N\ ]$
- node x:
  - knows cost to each neighbor v: $c(x,v)$
  - maintains its neighbors' distance vectors. For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N\ ]$

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance vector algorithm

iterative, asynchronous:
each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

each node:

wait for (change in local link cost or msg from neighbor)

recompute estimates

if DV to any dest has changed, *notify* neighbors

$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\} = \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\} = \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ *cost to*	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ *cost to*	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

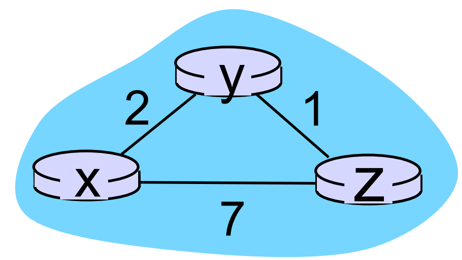
node y table

from \ *cost to*	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ *cost to*	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

time



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y	2	0	1
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

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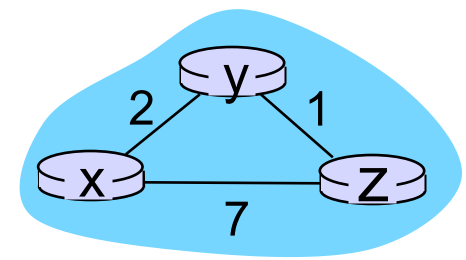
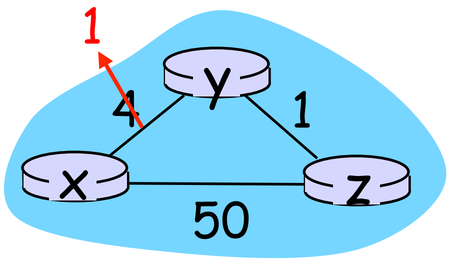


time

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors.

t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends its neighbors its DV.

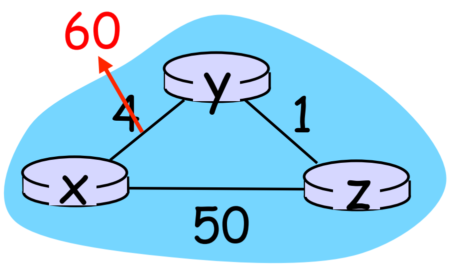
t_2 : *y* receives *z*' s update, updates its distance table. *y*' s least costs do *not* change, so *y* does *not* send a message to *z*.

* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- *bad news travels slow* - "count to infinity" problem!
- 44 iterations before algorithm stabilizes: see text



poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Comparison of LS and DV algorithms

message complexity

- ***LS:*** with n nodes, E links, O(nE) msgs sent
- ***DV:*** exchange between neighbors only
  - convergence time varies

speed of convergence

- ***LS:*** O(n^2) algorithm requires O(nE) msgs
  - may have oscillations
- ***DV:*** convergence time varies
  - may be routing loops
  - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its *own* table

DV:

- DV node can advertise incorrect *path* cost
- each node's table used by others
  - error propagate thru network

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Making routing scalable

our routing study thus far - idealized

- all routers identical
- network "flat"

… *not* true in practice

scale: with billions of destinations:

- can't store all destinations in routing tables!
- routing table exchange would swamp links!

administrative autonomy

- internet = network of networks
- each network admin may want to control routing in its own network

Internet approach to scalable routing

aggregate routers into regions known as "autonomous systems" (AS) (a.k.a. "domains")

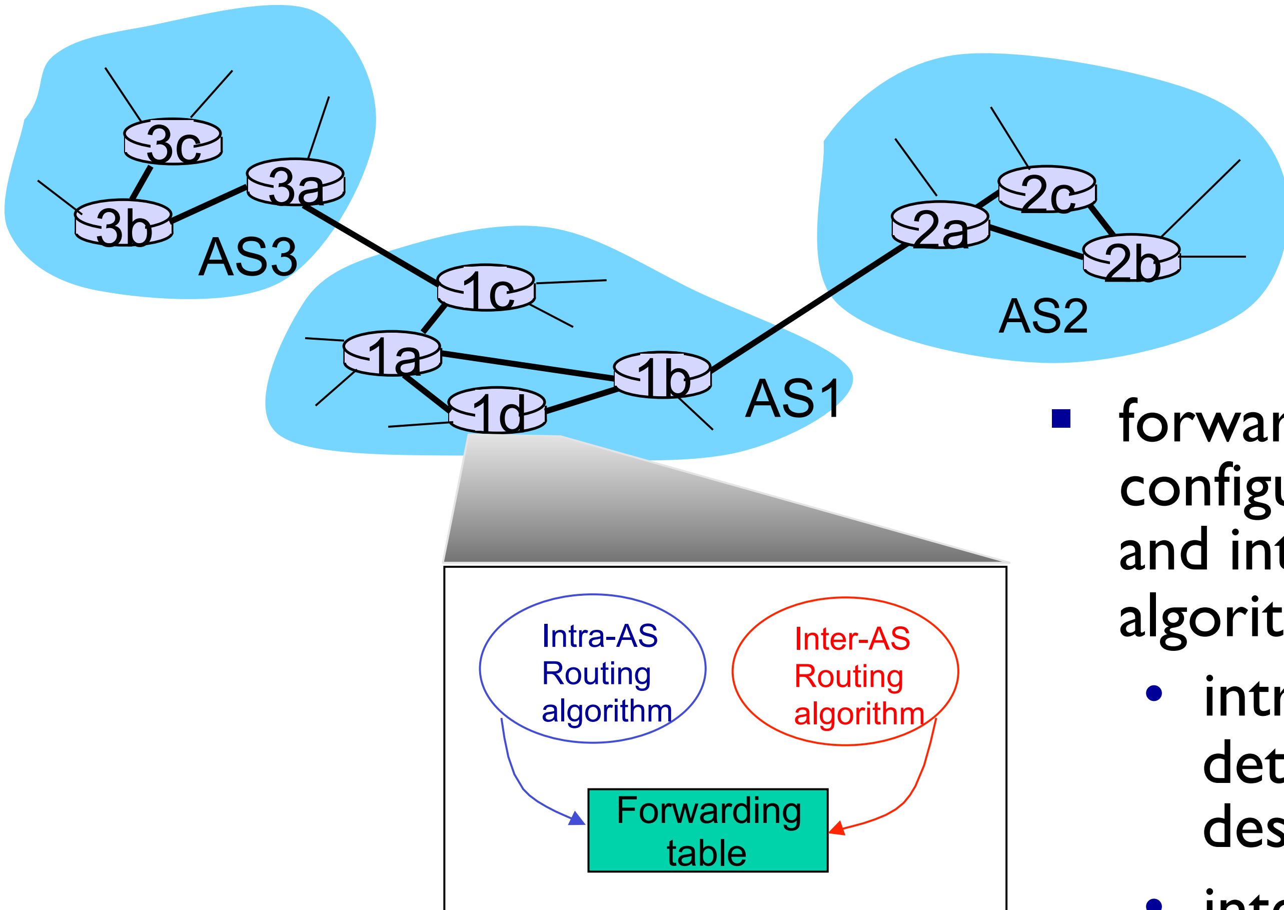
intra-AS routing

- routing among hosts, routers in same AS ("network")
- all routers in AS must run *same* intra-domain protocol
- routers in *different* AS can run *different* intra-domain routing protocol
- gateway router: at "edge" of its own AS, has link(s) to router(s) in other AS'es

inter-AS routing

- routing among AS'es
- gateways perform inter-domain routing (as well as intra-domain routing)

Interconnected ASes



- forwarding table configured by both intra- and inter-AS routing algorithm
  - intra-AS routing determine entries for destinations within AS
  - inter-AS & intra-AS determine entries for external destinations

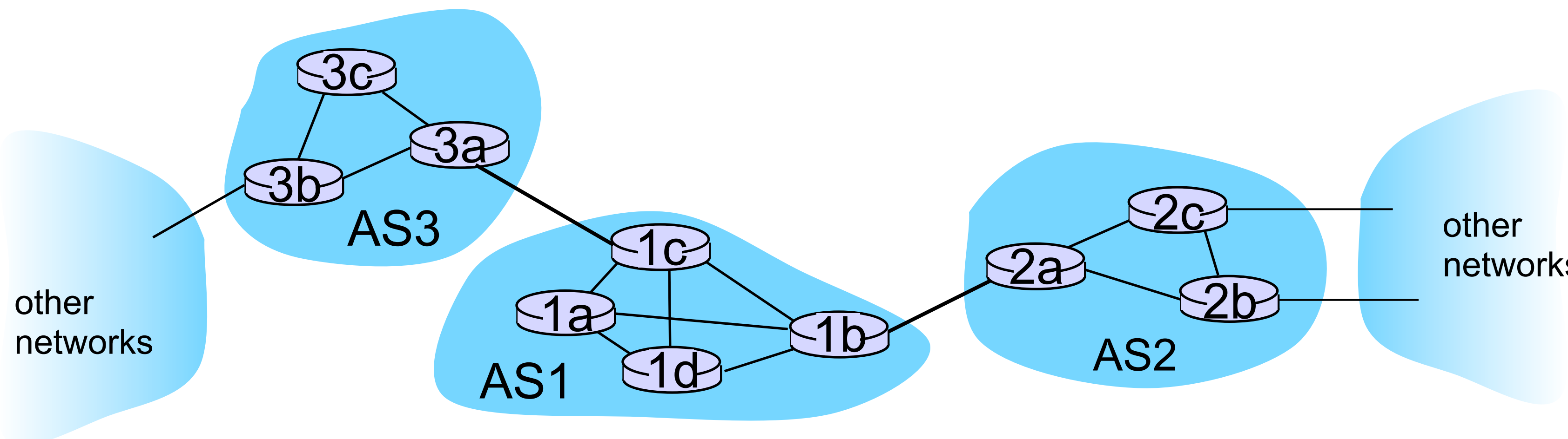
Inter-AS tasks

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router, but which one?

AS1 must:

1. learn which dests are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

job of inter-AS routing!



Intra-AS Routing

- also known as *interior gateway protocols (IGP)*
- most common intra-AS routing protocols:
  - RIP: Routing Information Protocol
  - OSPF: Open Shortest Path First (IS-IS protocol essentially same as OSPF)
  - IGRP: Interior Gateway Routing Protocol (Cisco proprietary for decades, until 2016)

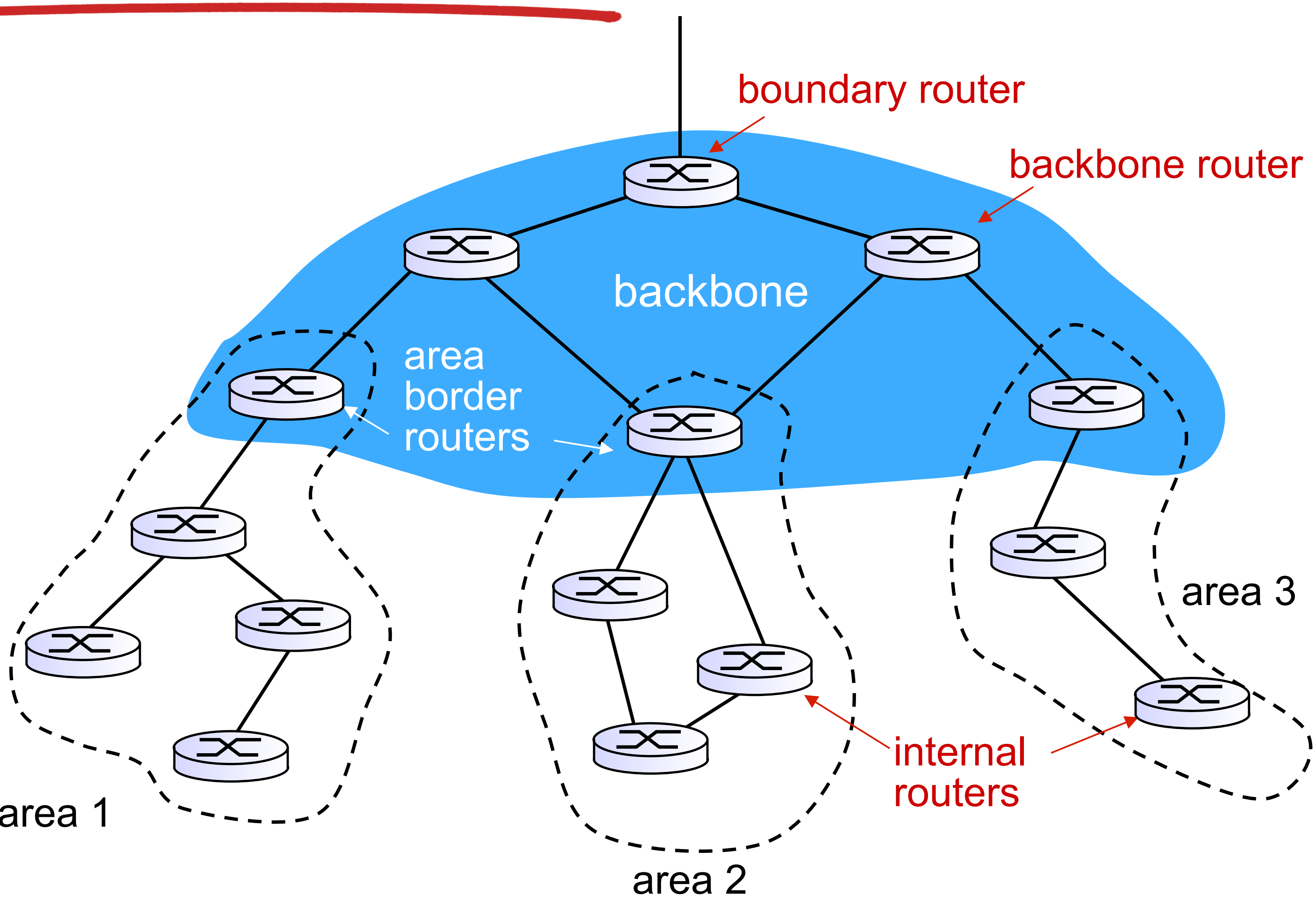
OSPF (Open Shortest Path First)

- "open": publicly available
- uses link-state algorithm
  - link state packet dissemination
  - topology map at each node
  - route computation using Dijkstra's algorithm
- router floods OSPF link-state advertisements to all other routers in *entire* AS
  - carried in OSPF messages directly over IP (rather than TCP or UDP
  - link state: for each attached link
- *IS-IS routing* protocol: nearly identical to OSPF

OSPF "advanced" features

- *security:* all OSPF messages authenticated (to prevent malicious intrusion)
- multiple same-cost paths allowed (only one path in RIP)
- for each link, multiple cost metrics for different TOS (e.g., satellite link cost set low for best effort ToS; high for real-time ToS)
- integrated uni- and multi-cast support:
  - Multicast OSPF (MOSPF) uses same topology data base as OSPF
- hierarchical OSPF in large domains.

Hierarchical OSPF



Hierarchical OSPF

- *two-level hierarchy:* local area, backbone.
  - link-state advertisements only in area
  - each nodes has detailed area topology; only know direction (shortest path) to nets in other areas.
- *area border routers:* "summarize" distances to nets in own area, advertise to other Area Border routers.
- *backbone routers:* run OSPF routing limited to backbone.
- *boundary routers:* connect to other AS' es.

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