Artificial General Intelligence 6. Operations and Goals

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Digital Futures (KTH, SU, RISE) Stockholm, Fall 2022

Events, operations, and goals

- Event: statement with time-specific truth-value
- Time specification
 - Relative: sequential and parallel events
 - Absolute: system clock (inference cycles)
 - Conceptual: terms with time-related meaning
- Operation: event realizable by the system
- Goal: event to be realized by the system (as task)
- Influence of <u>logic programming</u>

Reasoning on events

- Consider logical and temporal factors in parallel
 Prediction/explanation as temporal implication: precondition =/> postcondition
- Procedural knowledge (schema):

(precondition, operation) =/> consequence

Classical conditioning and operant conditioning: hypotheses generating, testing, and revising
Confident hypotheses become knowledge

Causal reasoning

- Causal knowledge: most reliable predictive relation, represented as predictive *implication* or *equivalence*, with domain-specific requirements
- Multiple ways to establish causal knowledge:
 - temporal induction ("association")
 - active experiment ("intervention")
 - hypothetical deduction ("counterfactual")
- Their differences are relative and quantitative

Goals and desires

- Initial goals are either implanted or imposed from the outside by the designers and users
- Derived goals are generated via backward inference until operations are reached
- The coexistent goals are not necessarily consistent with each other
- The *desire-value* of an event summarizes its relationship with the goals, and highly desired events become *active* goals

Operations

- Operations can be either internal (built-in and executed by NARS) or external (registered and executed by a connected device)
- In principle, NARS can connect with any software or hardware as a plug-in tool
- External operations are converted to devicespecific commands with return values
- NARS is being used to control robots and virtual characters with various "bodies"

Perception

Perception recognize temporal-spatial relations,

- generates *subjective* beliefs
- are *active* behaviors
- are *unified* with cognition



(S, shift(3, 0), T) \rightarrow left_arrow S \rightarrow rectangle, T \rightarrow triangle

To be used with machine learning tools and sources (Yolo, ImageNet, ...)



Hierarchical composition

- Like other terms, complicated operations and perceptions are represented by compound terms
- Compound terms are evaluated with priority values summarizing factors including
 - its innate features (simplicity, truth-value, ...)
 - its number of occurrence in experience and usefulness in task processing
 - its relevance to the current situation

Mental operation

- Some internal operations directly work on the system's reasoning process
- This *internal sensorimotor mechanism* is similar to the *external* one, except it's abstract and general
- Self-awareness: entering selected events into internal experience
- Self-control: intervening the system's inference procedures

Feeling and emotion

- Roughly speaking, for an event
- satisfaction-value = 1 |desire-value truth-value|
- Overall feelings of the system: *satisfaction, alertness, busyness, well-being*
- The *desire-value* of other (non-event) terms are determined by its correlated *satisfaction*
- Complex emotions are formed from the basic ones and influence resource-allocation

Consciousness

- Internal experience is incomplete and uncertain
- The system's self-description is different from third-person descriptions of its internal events
- Conscious and unconscious thinking processes follow the same logic
- Free will and causality co-exist as different perspectives
- AGI systems will be emotional and conscious, but not exactly like human in their contents Artificial General Intelligence

Suggested Readings

- Bernardo Pires, <u>Try Logic Programming -- A</u> <u>gentle introduction to Prolog</u>
- Alva Nöe, <u>Action in Perception</u>
- Jean-Marc Fellous, Michael A. Arbib, <u>Who Needs</u>
 <u>Emotions?: The Brain Meets the Robot</u>
- Pei Wang, <u>Perception in NARS</u>
- Pei Wang, Non-Axiomatic Logic, Chapter 11-13
- Pei Wang, Rigid Flexibility, Chapter 5