# MATRICES

## (slightly modified content from Wikipedia articles on matrices http://en.wikipedia.org/wiki/Matrix (mathematics))

A *matrix* is a rectangular array of <u>numbers</u> or other mathematical objects, for which operations such as <u>addition</u> and <u>multiplication</u> are defined. Most of this article focuses on *real matrices*, i.e., matrices whose elements are <u>real numbers</u>. For instance, this is a real matrix:

 $\mathbf{A} = \begin{bmatrix} -1.3 & 0.6\\ 20.4 & 5.5\\ 9.7 & -6.2 \end{bmatrix}.$ 

The numbers, symbols or expressions in the matrix are called its *entries* or its *elements*. The horizontal and vertical lines of entries in a matrix are called *rows* and *columns*, respectively. The size of a matrix is defined by the number of rows and columns that it contains. A matrix with *m* rows and *n* columns is called an  $m \times n$  matrix or *m*-by-*n* matrix, while *m* and *n* are called its *dimensions*. For example, the matrix A above is a  $3 \times 2$  matrix. Matrices which have a single row are called *row vectors*, and those which have a single column are called *column vectors*. A matrix which has the same number of rows and columns is called a *square matrix*.

Name Size Example			Description			
Row vector	$1 \times n$ [3	3 7 2]	A matrix with one row, sometimes used to represent a vector			
Column vecto	<mark>r</mark> <i>n</i> × 1	$\begin{bmatrix} 4\\1\\8\end{bmatrix}$	A matrix with one column, sometimes used to represent a vector			
<u>Square matrix</u>	$n \times n \begin{bmatrix} 9\\1\\2 \end{bmatrix}$	$\begin{array}{ccc} 13 & 5 \\ 11 & 7 \\ 6 & 3 \end{array}$	A matrix with the same number of rows and columns.			

# 1. Notation

Matrices are commonly written in box brackets:

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.$$

The specifics of symbolic matrix notation varies widely, with some prevailing trends. Matrices are usually symbolized using <u>upper-case</u> letters (such as A in the examples above), while the corresponding lower-case letters, with two subscript indices (e.g.,  $a_{11}$ , or  $a_{1,1}$ ), represent the entries.

The entry in the *i*-th row and *j*-th column of a matrix **A** is sometimes referred to as the i,j, (i,j), or (i,j)<sup>th</sup> entry of the matrix, and most commonly denoted as  $a_{i,j}$ , or  $a_{ij}$ . Alternative notations for that entry are A[i,j] or  $A_{i,j}$ . For example, the (1,3) entry of the following matrix **A** is 5 (also denoted  $a_{13}$ ,  $a_{1,3}, A[1,3]$  or  $A_{1,3}$ ):

 $\mathbf{A} = \begin{bmatrix} 4 & -7 & 5 & 0 \\ -2 & 0 & 11 & 8 \\ 19 & 1 & -3 & 12 \end{bmatrix}$ 

Sometimes, the entries of a matrix can be defined by a formula such as  $a_{i,j} = f(i, j)$ . For example, each of the entries of the following matrix **A** is determined by  $a_{ij} = i - j$ .

 $\mathbf{A} = \begin{bmatrix} 0 & -1 & -2 & -3 \\ 1 & 0 & -1 & -2 \\ 2 & 1 & 0 & -1 \end{bmatrix}$ 

In this case, the matrix itself is sometimes defined by that formula, within square brackets or double parenthesis. For example, the matrix above is defined as  $\mathbf{A} = [i-j]$ . If matrix size is  $m \times n$ , the above-mentioned formula f(i, j) is valid for any i = 1, ..., m and any j = 1, ..., n. This can be either specified separately, or using  $m \times n$  as a subscript. For instance, the matrix  $\mathbf{A}$  above is  $3 \times 4$  and can be defined as  $\mathbf{A} = [i-j]$  (i = 1, 2, 3; j = 1, ..., 4), or  $\mathbf{A} = [i-j]_{3 \times 4}$ .

#### Submatrix

A **submatrix** of a matrix is obtained by deleting any collection of rows and/or columns. For example, from the following 3-by-4 matrix, we can construct a 2-by-3 submatrix by removing row 3 and column 2:

 $\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 4 \\ 5 & 7 & 8 \end{bmatrix}.$ 

A principal submatrix is a square submatrix obtained by removing certain rows and columns. A leading principal submatrix is one in which the first *k* rows and columns, for some number *k*, are the ones that remain.

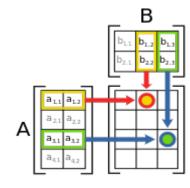
## 2. Basic operations

There are a number of basic operations that can be applied to modify matrices, called *matrix addition*, *scalar multiplication*, *transposition*, *matrix multiplication*, *row operations*, and *submatrix*.

Operation	Definition	Example
Addition	The sum $\mathbf{A}+\mathbf{B}$ of two <i>m</i> -by- <i>n</i> matrices $\mathbf{A}$ and $\mathbf{B}$ is calculated entrywise: $(\mathbf{A} + \mathbf{B})_{i,j} = \mathbf{A}_{i,j} + \mathbf{B}_{i,j}$ , where $1 \le i \le m$ and $1 \le j \le n$ .	$\begin{bmatrix} 1 & 3 & 1 \\ 1 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 5 \\ 7 & 5 & 0 \end{bmatrix} = \begin{bmatrix} 1+0 & 3+0 & 1+5 \\ 1+7 & 0+5 & 0+0 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 6 \\ 8 & 5 & 0 \end{bmatrix}$
<u>Scalar</u> multiplication	The product $c\mathbf{A}$ of a number $c$ (also called a <u>scalar</u> ) and a matrix $\mathbf{A}$ is computed by multiplying every entry of $\mathbf{A}$ by $c$ : $(c\mathbf{A})_{i,j} = c \cdot \mathbf{A}_{i,j}.$	$2 \cdot \begin{bmatrix} 1 & 8 & -3 \\ 4 & -2 & 5 \end{bmatrix} = \begin{bmatrix} 2 \cdot 1 & 2 \cdot 8 & 2 \cdot -3 \\ 2 \cdot 4 & 2 \cdot -2 & 2 \cdot 5 \end{bmatrix} = \begin{bmatrix} 2 & 16 & -6 \\ 8 & -4 & 10 \end{bmatrix}$
<u>Transposition</u>	This operation is called <i>scalar multiplication</i> . The <i>transpose</i> of an <i>m</i> -by- <i>n</i> matrix <b>A</b> is the <i>n</i> -by- <i>m</i> matrix $\mathbf{A}^{\mathrm{T}}$ formed by turning rows into columns and vice versa: $(\mathbf{A}^{\mathrm{T}})_{i,j} = \mathbf{A}_{j,i}$ .	$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -6 & 7 \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} 1 & 0 \\ 2 & -6 \\ 3 & 7 \end{bmatrix}$

Familiar properties of numbers extend to these operations of matrices: for example, addition is <u>commutative</u>, i.e., the matrix sum does not depend on the order of the summands:  $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$ . The transpose is compatible with addition and scalar multiplication, as expressed by  $(c\mathbf{A})^{T} = c(\mathbf{A}^{T})$  and  $(\mathbf{A} + \mathbf{B})^{T} = \mathbf{A}^{T} + \mathbf{B}^{T}$ . Finally,  $(\mathbf{A}^{T})^{T} = \mathbf{A}$ .

## **Matrix multiplication**



Schematic depiction of the matrix product **AB** of two matrices **A** and **B**.

*Multiplication* of two matrices is defined if and only if the number of columns of the left matrix is the same as the number of rows of the right matrix. If **A** is an *m*-by-*n* matrix and **B** is an *n*-by-*p* matrix, then their *matrix product* **AB** is the *m*-by-*p* matrix whose entries are given by dot product of the corresponding row of **A** and the corresponding column of **B**:

$$[\mathbf{AB}]_{i,j} = A_{i,1}B_{1,j} + A_{i,2}B_{2,j} + \dots + A_{i,n}B_{n,j} = \sum_{r=1}^{n} A_{i,r}B_{r,r}$$

where  $1 \le i \le m$  and  $1 \le j \le p$ .<sup>[12]</sup> For example, the underlined entry 2340 in the product is calculated as  $(2 \times 1000) + (3 \times 100) + (4 \times 10) = 2340$ :

 $\begin{bmatrix} 2 & 3 & 4 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & \underline{1000} \\ 1 & \underline{100} \\ 0 & \underline{10} \end{bmatrix} = \begin{bmatrix} 3 & \underline{2340} \\ 0 & \underline{1000} \end{bmatrix}.$ 

Matrix multiplication satisfies the rules (AB)C = A(BC) (associativity), and (A+B)C = AC+BC as well as C(A+B) = CA+CB (left and right distributivity), whenever the size of the matrices is such that the various products are defined.<sup>[13]</sup> The product AB may be defined without BA being defined, namely if A and B are *m*-by-*n* and *n*-by-*k* matrices, respectively, and  $m \neq k$ . Even if both products are defined, they need not be equal, i.e., generally

#### <mark>AB ≠ BA,</mark>

i.e., *matrix multiplication is not <u>commutative</u>*, in marked contrast to (rational, real, or complex) numbers whose product is independent of the order of the factors. An example of two matrices not commuting with each other is:

1	2][0	1]	_ 0	1]	0	1][1	2]	3	4
3	4 ] 0	0	- 0	$\begin{bmatrix} 1\\ 3 \end{bmatrix}$ , whereas	0	0 ] [3]	4	0	0].

The following property for transpose of the matrix product can be shown to hold:  $(AB)^{T} = B^{T}A^{T}$ 

## **Elementary Row Matrix (and Column) Operations**

There are three types of row operations on a matrix **A** of dimension *m*-by-*n* that can be produced by multiplying it from left with an elementary matrix **E** of dimension *m*-by-*m*, EA:

- 1. row switching, that is interchanging two rows of a matrix.
- 2. row addition, that is adding a row to another.
- 3. row multiplication, that is multiplying all entries of a row by a non-zero constant.

In <u>mathematics</u>, an **elementary matrix** is a <u>matrix</u> which differs from the <u>identity matrix</u> by one single elementary row operation. Repeated multiplication of the identity matrix by the elementary matrices can generate any <u>invertible matrix</u> (definition of the inverse matrix will come later). Left multiplication (pre-multiplication) by an elementary matrix represents **elementary row operations**, while right multiplication (post-multiplication) represents **elementary column operations**. Elementary row operations are the basis of the very important method of <u>Gaussian</u> <u>elimination</u> (will be explained below).

## **Row-switching transformations**

The first type of row operation on a matrix  $\mathbf{A}$  switches all matrix elements on row *i* with their counterparts on row *j*. The corresponding elementary matrix is obtained by swapping row *i* and row *j* of the <u>identity matrix</u>.

$$T_{i,j} = \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 0 & 1 & & \\ & & & \ddots & & \\ & & 1 & 0 & & \\ & & & & \ddots & \\ & & & & & 1 \end{bmatrix}$$

So  $\mathbf{T}_{ij} \cdot \mathbf{A}$  is the matrix produced by exchanging row *i* and row *j* of  $\mathbf{A}$ .

## **Row-multiplying transformations**

The next type of row operation on a matrix  $\mathbf{A}$  multiplies all elements on row *i* by *m* where *m* is a non-zero scalar (usually a real number). The corresponding elementary matrix is a diagonal matrix, with diagonal entries 1 everywhere except in the *i*th position, where it is *m*.

 $T_i(m) = \begin{bmatrix} 1 & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & m & & \\ & & & & 1 & & \\ & & & & \ddots & \\ & & & & & & 1 \end{bmatrix}$ 

So  $\mathbf{T}_i(m) \cdot \mathbf{A}$  is the matrix produced from **A** by multiplying row *i* by *m*.

## **Row-addition transformations**

The final type of row operation on a matrix  $\mathbf{A}$  adds row *j* multiplied by a scalar *m* to row *i*. The corresponding elementary matrix is the identity matrix but with an *m* in the (i,j) position.

$$T_{i,j}(m) = \begin{bmatrix} 1 & & & & \\ & \ddots & & & \\ & & 1 & & \\ & & & \ddots & \\ & & m & 1 & \\ & & & & \ddots & \\ & & & & & 1 \end{bmatrix}$$

So  $\mathbf{T}_{i,j}(m) \cdot \mathbf{A}$  is the matrix produced from **A** by adding *m* times row *j* to row *i*.

Examples:

M\*A adds 2 times row 1 to row 3:

$$MA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 5 & 5 & 5 \end{bmatrix}$$

M\*A adds 4 times row 2 to row 1:

 $MA = \begin{bmatrix} 1 & 4 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix} = \begin{bmatrix} 9 & 9 & 9 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$