

Parameter Estimation in Probabilistic Models, Linear Regression and Logistic Regression

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CS5350/6350: Machine Learning

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- Independent and Identically Distributed:
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- **Goal:** Estimate parameter θ that best models/describes the data
- Several ways to define the “best”

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- While doing MAP, we usually maximize the **log of the posterior probability**

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- MAP allows incorporating our **prior knowledge** about θ in its estimation

Linear Regression: The Probabilistic Formulation

- Each response generated by a linear model plus some Gaussian noise

$$y = \mathbf{w}^T \mathbf{x} + \epsilon$$

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- Given data $\mathcal{D} = \{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)\}$, we want to estimate the weight vector \mathbf{w}

Linear Regression: Maximum Likelihood Solution

- Log-likelihood:

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- For $\sigma = 1$ (or some constant) for each input, it's equivalent to the least-squares objective for linear regression

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- Let's assume a **Gaussian prior distribution** over the weight vector \mathbf{w}

$$P(\mathbf{w}) = \mathcal{N}(\mathbf{w} \mid 0, \lambda^{-1}\mathbf{I}) = \frac{1}{(2\pi)^{D/2}} \exp\left(-\frac{\lambda}{2} \mathbf{w}^\top \mathbf{w}\right)$$

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- For $\sigma = 1$ (or some constant) for each input, it's equivalent to the **regularized** least-squares objective

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Probabilistic Classification: Logistic Regression

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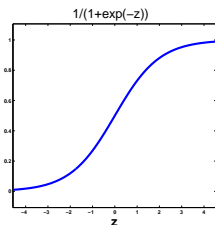
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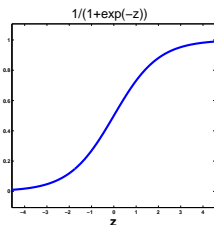
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- This is the Logistic Regression model
 - **Misnomer:** Logistic Regression is a classification model :-)



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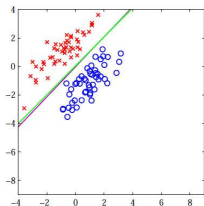
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- The decision boundary is therefore **linear** \Rightarrow Logistic Regression is a linear classifier (note: it's possible to kernelize and make it nonlinear)



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$$P(\mathbf{w}) = \mathcal{N}(\mathbf{w} \mid 0, \lambda^{-1}\mathbf{I}) = \frac{1}{(2\pi)^{D/2}} \exp\left(-\frac{\lambda}{2} \mathbf{w}^\top \mathbf{w}\right)$$

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- See “A comparison of numerical optimizers for logistic regression” by Tom Minka on optimization techniques (gradient descent and others) for logistic regression (both MLE and MAP)

Logistic Regression: MLE vs MAP (summary)

- MLE solution:

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- Note: For MAP, different prior distributions lead to different regularizers
 - Gaussian prior on \mathbf{w} regularizes the ℓ_2 norm of \mathbf{w}
 - Laplace prior $\exp(-C\|\mathbf{w}\|_1)$ on \mathbf{w} regularizes the ℓ_1 norm of \mathbf{w}

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- Possible to kernelize it to learn nonlinear boundaries

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