# Supervised Learning: *K*-Nearest Neighbors and Decision Trees

## Piyush Rai

CS5350/6350: Machine Learning

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Modified by Longin Jan Latecki

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- *N* input/output pairs;  $\mathbf{x}_i$  input,  $\mathbf{y}_i$  output/label

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- Goal: predict the output y for an unseen test example x
- This lecture: Two intuitive methods
  - K-Nearest-Neighbors
  - Decision Trees

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Image: A = A

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- Special Case: 1-Nearest Neighbor

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• Unlike other supervised learning algorithms, *K*-Nearest Neighbors doesn't learn an explicit mapping *f* from the training data

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**Note:** *K*-Nearest Neighbors is called a *non-parametric* method

- Unlike other supervised learning algorithms, *K*-Nearest Neighbors doesn't learn an explicit mapping *f* from the training data
- It simply uses the training data at the test time to make predictions

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$$d(\mathbf{x}_i, \mathbf{x}_j) = \sqrt{\sum_{m=1}^{D} (x_{im} - x_{jm})^2} = \sqrt{||\mathbf{x}_i||^2 + ||\mathbf{x}_j||^2 - 2\mathbf{x}_i^T \mathbf{x}_j}$$

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Norm of a vector x is also its length

•  $\mathbf{x}_i^T \mathbf{x}_j = \sum_{m=1}^{D} x_{im} x_{jm}$  is called the **dot (or inner) product** of  $\mathbf{x}_i$  and  $\mathbf{x}_j$ 

• Dot product measures the **similarity** between two vectors (orthogonal vectors have dot product=0, parallel vectors have high dot product)

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  - $\bar{x_m} = \frac{1}{N} \sum_{i=1}^{N} x_{im}$ : empirical mean of  $m^{th}$  feature
  - $\sigma_m^2 = \frac{1}{N} \sum_{i=1}^{N} (x_{im} \bar{x_m})^2$ : empirical variance of  $m^{th}$  feature

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## K-NN: Some other distance measures

- Binary-valued features
  - Use Hamming distance:  $d(x_i, x_j) = \sum_{m=1}^{D} \mathbb{I}(x_{im} \neq x_{jm})$
  - Hamming distance counts the number of features where the two examples disagree
- Mixed feature types (some real-valued and some binary-valued)?
  - Can use mixed distance measures
  - E.g., Euclidean for the real part, Hamming for the binary part
- Can also assign weights to features:  $d(x_i, x_j) = \sum_{m=1}^{D} w_m d(x_{im}, x_{jm})$

## Choice of K - Neighborhood Size



## Small K

- Creates many small regions for each class
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  - Creates fewer larger regions
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- Choosing K
  - Often data dependent and heuristic based
  - Or using cross-validation (using some held-out data)
  - In general, a K too small or too big is bad!

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#### • What's not so nice..

- Store all the training data in memory even at test time
  - Can be memory intensive for large training datasets
  - An example of non-parametric, or memory/instance-based methods
  - Different from parametric, model-based learning models

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- Store all the training data in memory even at test time
  - Can be memory intensive for large training datasets
  - An example of non-parametric, or memory/instance-based methods
  - Different from parametric, model-based learning models
- Expensive at test time: O(ND) computations for each test point
  - Have to search through all training data to find nearest neighbors
  - Distance computations with N training points (D features each)

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- Asymptotically consistent (a theoretical property)
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- May perform badly in high dimensions (curse of dimensionality)
  - In high dimensions, distance notions can be counter-intuitive!

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(a)

- Computational speed-ups (don't want to spend O(ND) time)
  - Improved data structures for fast nearest neighbor search
  - Even if *approximately* nearest neighbors, yet may be good enough
- Efficient Storage (don't want to store all the training data)
  - E.g., subsampling the training data to retain "prototypes"
  - Leads to computational speed-ups too!
- Metric Learning: Learning the "right" distance metric for a given dataset

# kd-trees

