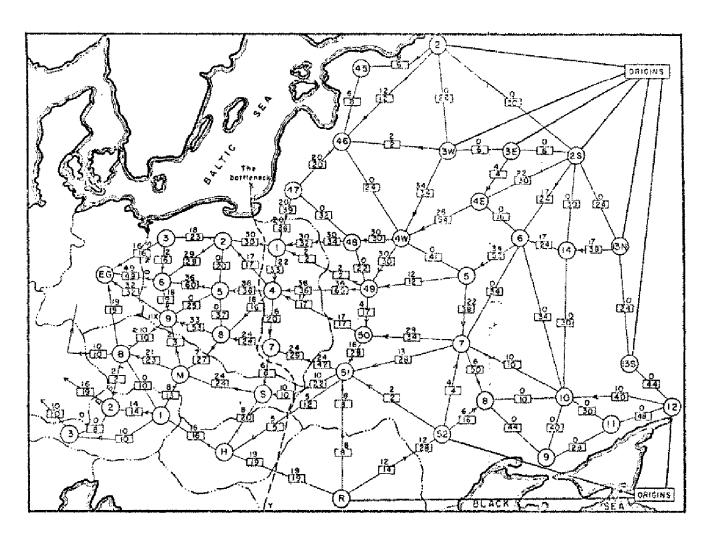


Chapter 7

Network Flow



Soviet Rail Network, 1955



Reference: On the history of the transportation and maximum flow problems. Alexander Schrijver in Math Programming, 91: 3, 2002.

Maximum Flow and Minimum Cut

Max flow and min cut.

Two very rich algorithmic problems.

Cornerstone problems in combinatorial optimization.

Beautiful mathematical duality.

Nontrivial applications / reductions.

Network connectivity.

Data mining. Network reliability.

Open-pit mining. Distributed computing.

Project selection. Egalitarian stable matching.

Airline scheduling. Security of statistical data.

Network intrusion detection. Bipartite matching.

Baseball elimination. Multi-camera scene reconstruction.

Image segmentation. Many many more ...

Minimum Cut Problem

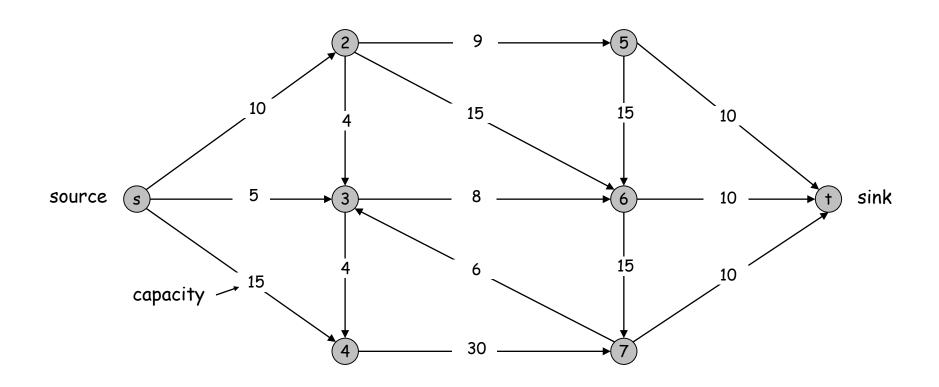
Flow network.

Abstraction for material flowing through the edges.

G = (V, E) = directed graph, no parallel edges.

Two distinguished nodes: s = source, t = sink.

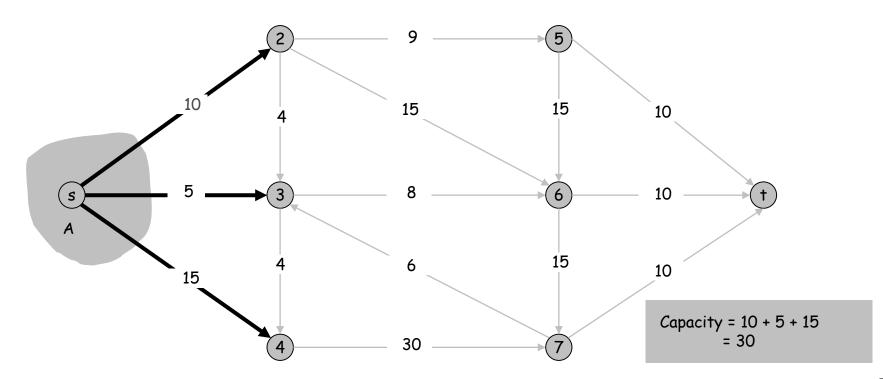
c(e) = capacity of edge e.



Cuts

Def. An s-t cut is a partition (A, B) of V with $s \in A$ and $t \in B$.

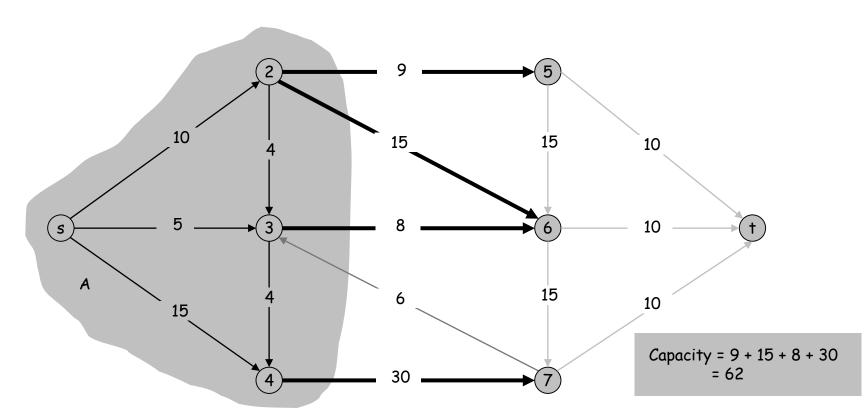
Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



Cuts

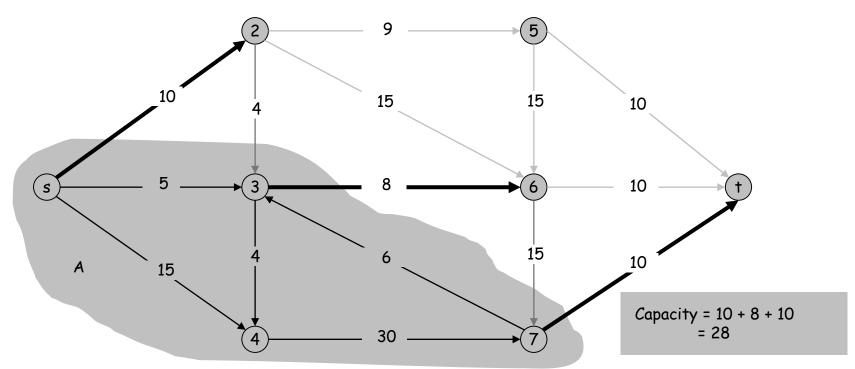
Def. An s-t cut is a partition (A, B) of V with $s \in A$ and $t \in B$.

Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



Minimum Cut Problem

Min s-t cut problem. Find an s-t cut of minimum capacity.



Flows

Def. An s-t flow is a function that satisfies:

For each $e \in E$: $0 \le f(e) \le c(e)$

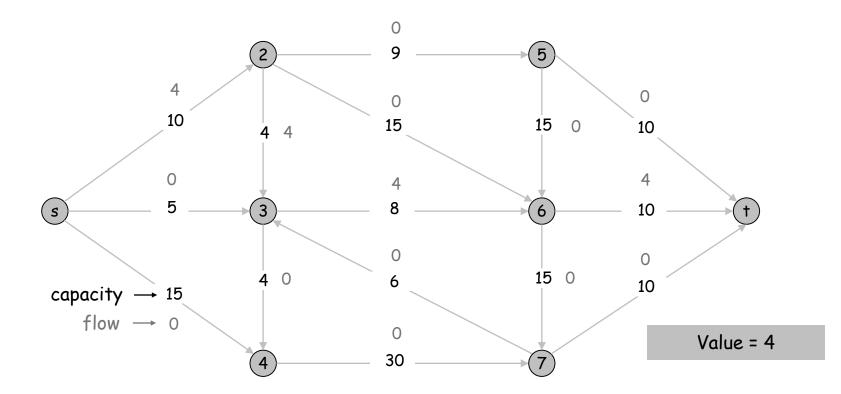
$$0 \le f(e) \le c(e)$$

For each $v \in V - \{s, t\}$: $\sum f(e) = \sum f(e)$

$$\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

[capacity] [conservation]

Def. The value of a flow f is: $v(f) = \sum f(e)$. e out of s



Flows

Def. An s-t flow is a function that satisfies:

For each $e \in E$:

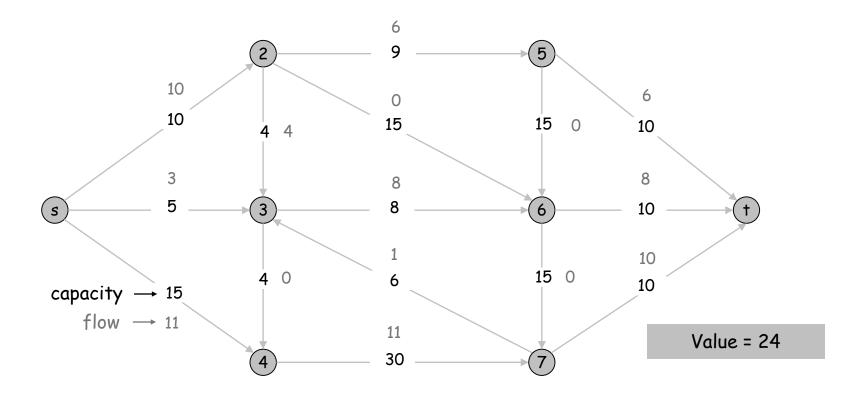
$$0 \le f(e) \le c(e)$$

For each $v \in V - \{s, t\}$: $\sum f(e) = \sum f(e)$

$$\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

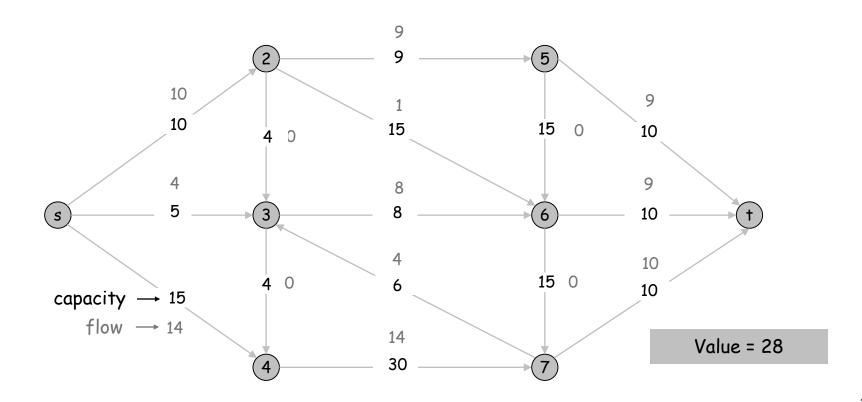
[capacity] [conservation]

Def. The value of a flow f is: $v(f) = \sum f(e)$. e out of s



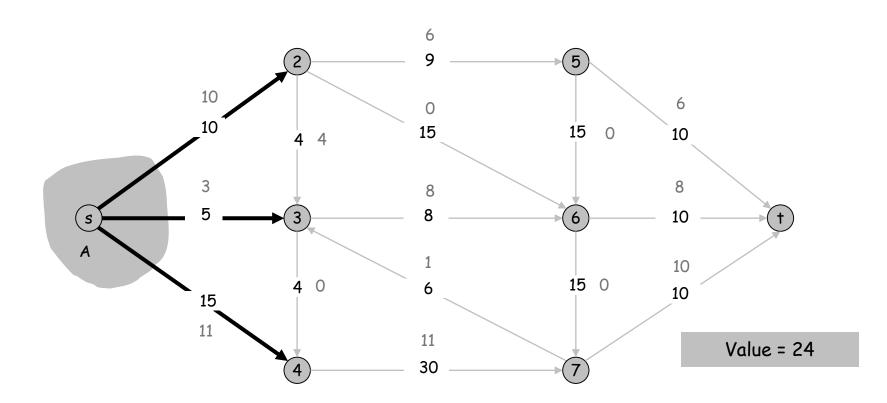
Maximum Flow Problem

Max flow problem. Find s-t flow of maximum value.



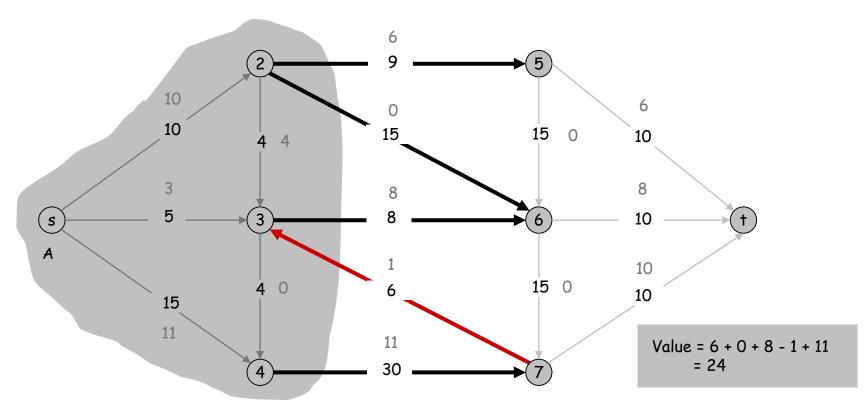
Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to A}} f(e) = v(f)$$



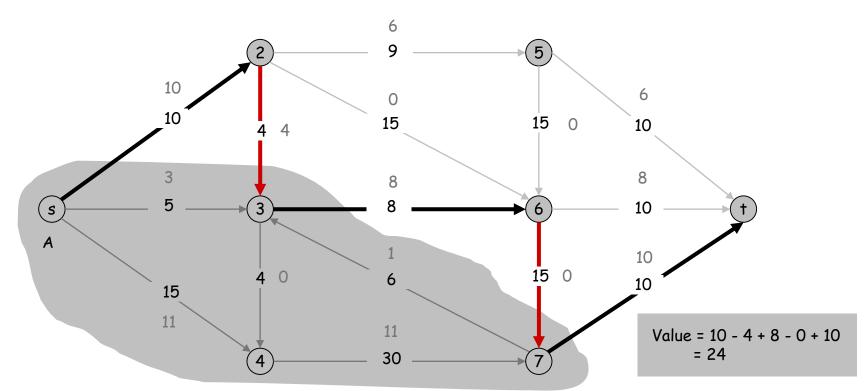
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Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then

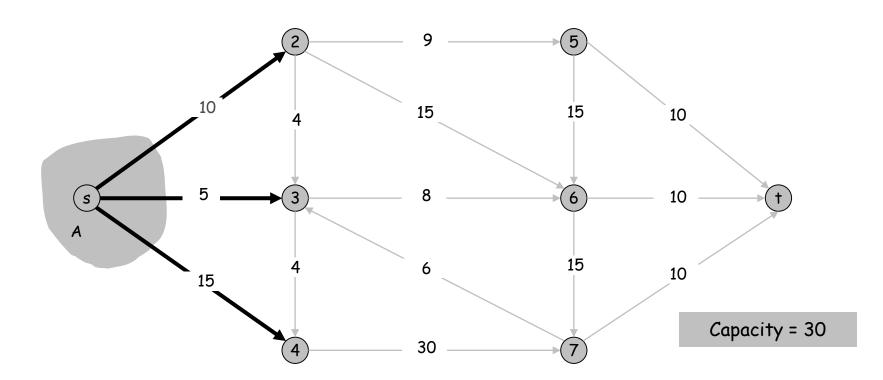
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

Pf.
$$v(f) = \sum_{e \text{ out of } s} f(e)$$
by flow conservation, all terms
$$= \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$$

$$= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e).$$

Weak duality. Let f be any flow, and let (A, B) be any s-t cut. Then the value of the flow is at most the capacity of the cut.

Cut capacity = $30 \Rightarrow \text{Flow value} \leq 30$



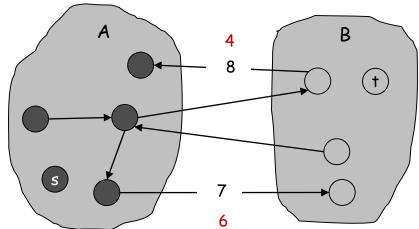
Weak duality. Let f be any flow. Then, for any s-t cut (A, B) we have $v(f) \le cap(A, B)$.

Pf.

$$v(f) = \sum_{\substack{e \text{ out of } A \\ e \text{ out of } A}} f(e) - \sum_{\substack{e \text{ in to } A \\ e \text{ out of } A}} f(e)$$

$$\leq \sum_{\substack{e \text{ out of } A \\ e \text{ out of } A}} f(e)$$

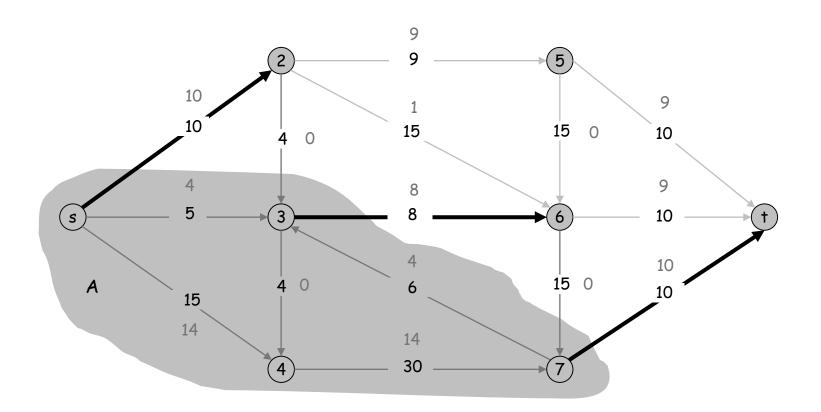
$$\leq \sum_{\substack{e \text{ out of } A \\ e \text{ out of } A}} f(e)$$



Certificate of Optimality

Corollary. Let f be any flow, and let (A, B) be any cut. If v(f) = cap(A, B), then f is a max flow and (A, B) is a min cut.

Value of flow = 28 Cut capacity = 28 \Rightarrow Flow value \leq 28



Towards a Max Flow Algorithm

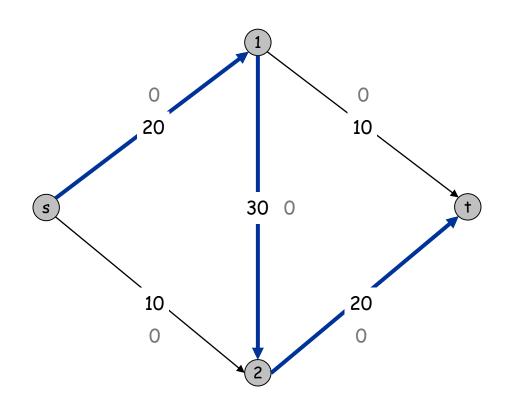
Greedy algorithm.

Start with f(e) = 0 for all edge $e \in E$.

Find an s-t path P where each edge has f(e) < c(e).

Augment flow along path P.

Repeat until you get stuck.



Flow value = 0

Towards a Max Flow Algorithm

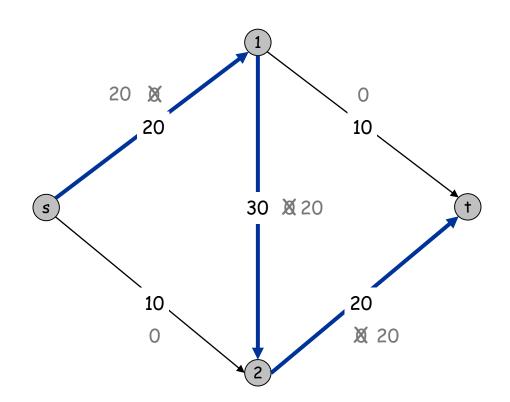
Greedy algorithm.

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Find an s-t path P where each edge has f(e) < c(e).

Augment flow along path P.

Repeat until you get stuck.



Flow value = 20

Towards a Max Flow Algorithm

Greedy algorithm.

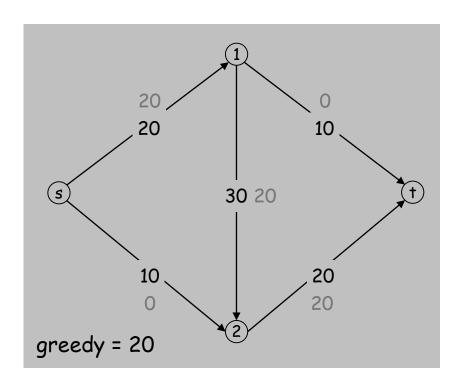
Start with f(e) = 0 for all edge $e \in E$.

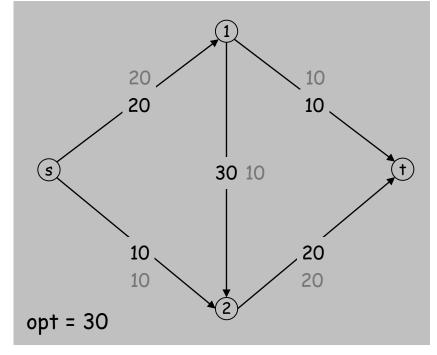
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Augment flow along path P.

Repeat until you get stuck.

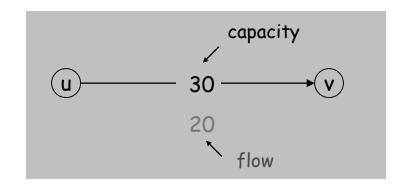
\(\) locally optimality \(\neq \) global optimality





Residual Graph

Original edge: $e = (u, v) \in E$. Flow f(e), capacity c(e).



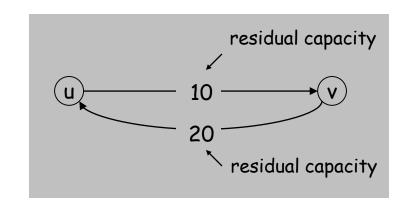
Residual edge.

"Undo" flow sent.

e = (u, v) and $e^{R} = (v, u)$.

Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$

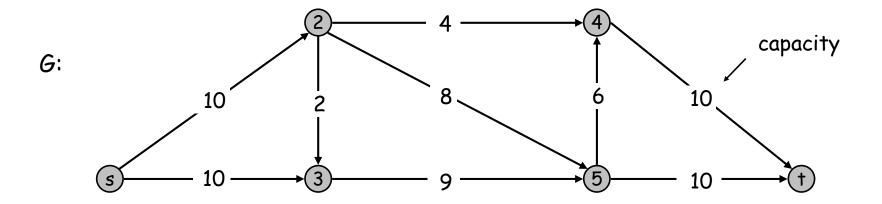


Residual graph: $G_f = (V, E_f)$.

Residual edges with positive residual capacity.

$$E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}.$$

Ford-Fulkerson Algorithm





Augmenting Path Algorithm

```
Augment(f, c, P) {
  b ← bottleneck(P)
  foreach e ∈ P {
    if (e ∈ E) f(e) ← f(e) + b forward edge
    else f(e<sup>R</sup>) ← f(e<sup>R</sup>) - b reverse edge
  }
  return f
}
```

```
Ford-Fulkerson(G, s, t, c) {
   foreach e ∈ E f(e) ← 0
   G<sub>f</sub> ← residual graph

while (there exists augmenting path P) {
   f ← Augment(f, c, P)
     update G<sub>f</sub>
   }
   return f
}
```

Max-Flow Min-Cut Theorem

Augmenting path theorem. Flow f is a max flow iff there are no augmenting paths.

Max-flow min-cut theorem. [Elias-Feinstein-Shannon 1956, Ford-Fulkerson 1956] The value of the max flow is equal to the value of the min cut.

- Pf. We prove both simultaneously by showing TFAE:
 - (i) There exists a cut (A, B) such that v(f) = cap(A, B).
 - (ii) Flow f is a max flow.
 - (iii) There is no augmenting path relative to f.
- (i) \Rightarrow (ii) This was the corollary to weak duality lemma.
- (ii) ⇒ (iii) We show contrapositive.
 Let f be a flow. If there exists an augmenting path, then we can improve f by sending flow along path.

Proof of Max-Flow Min-Cut Theorem

(iii)
$$\Rightarrow$$
 (i)

Let f be a flow with no augmenting paths.

Let A be set of vertices reachable from s in residual graph.

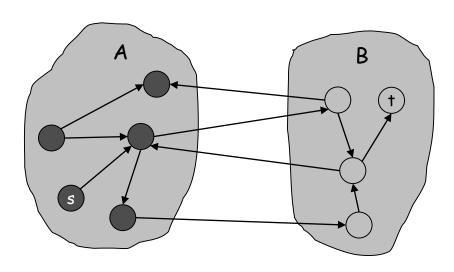
By definition of $A, s \in A$.

By definition of f, $t \notin A$.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$= \sum_{e \text{ out of } A} c(e)$$

$$= cap(A, B) \quad \blacksquare$$



original network

Running Time

Assumption. All capacities are integers between 1 and C.

Invariant. Every flow value f(e) and every residual capacity $c_f(e)$ remains an integer throughout the algorithm.

Theorem. The algorithm terminates in at most $v(f^*) \le nC$ iterations. Pf. Each augmentation increase value by at least 1. •

Corollary. If C = 1, Ford-Fulkerson runs in O(mn) time.

Integrality theorem. If all capacities are integers, then there exists a max flow f for which every flow value f(e) is an integer.

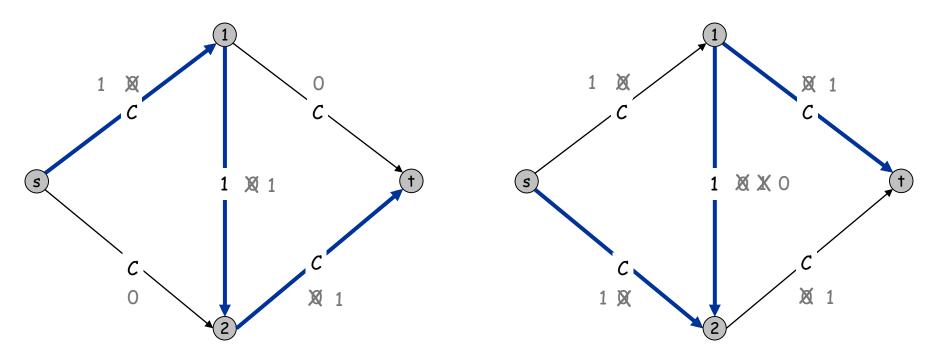
Pf. Since algorithm terminates, theorem follows from invariant. •

7.3 Choosing Good Augmenting Paths

Ford-Fulkerson: Exponential Number of Augmentations

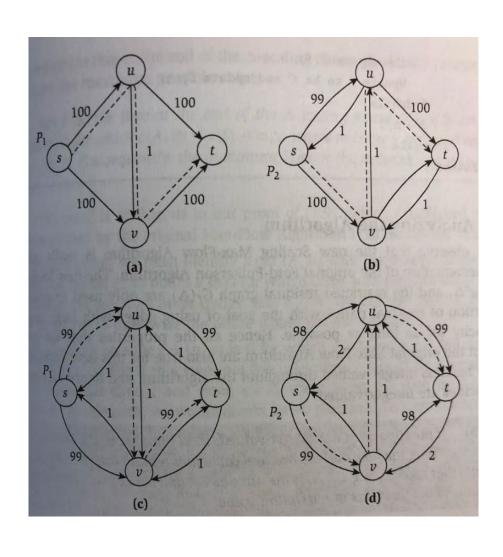
Q. Is generic Ford-Fulkerson algorithm polynomial in input size? m (# of edges), n (# of nodes), and log C

A. No. If max capacity is C, then algorithm can take C iterations.



Ford-Fulkerson: Exponential Number of Augmentations

C=100



Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

Some choices lead to exponential algorithms.

Clever choices lead to polynomial algorithms.

If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

Can find augmenting paths efficiently.

Few iterations.

Choose augmenting paths with:

Augmenting path with fewest number of edges [Edmonds-Karp 1972, Dinitz 1970]

Preflow-push maximum-flow (notion of node height) [Goldberg 1986] Both are strongly polynomial algorithms: O(mn)

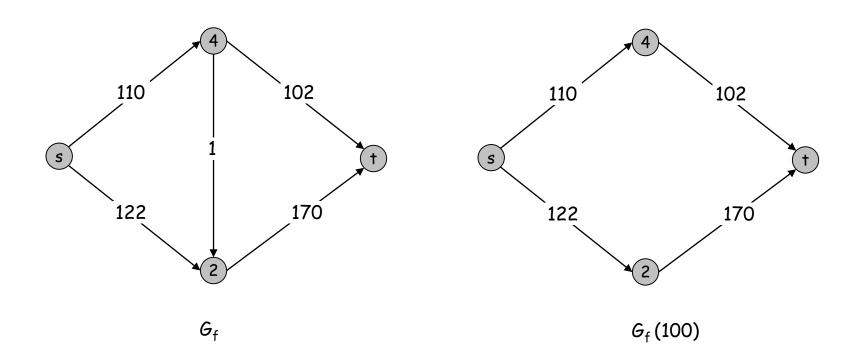
Capacity Scaling

Intuition. Choosing path with highest bottleneck capacity increases flow by max possible amount.

Don't worry about finding exact highest bottleneck path.

Maintain scaling parameter Δ .

Let $G_f(\Delta)$ be the subgraph of the residual graph consisting of only arcs with capacity at least Δ .



Capacity Scaling

```
Scaling-Max-Flow(G, s, t, c) {
    foreach e \in E f(e) \leftarrow 0
   \Delta \leftarrow smallest power of 2 greater than or equal to C
   G_f \leftarrow residual graph
   while (\Delta \geq 1) {
        G_f(\Delta) \leftarrow \Delta-residual graph
        while (there exists augmenting path P in G_f(\Delta)) {
            f \leftarrow augment(f, c, P)
            update G_f(\Delta)
       \Delta \leftarrow \Delta / 2
    return f
```

Capacity Scaling: Correctness

Assumption. All edge capacities are integers between 1 and C.

Integrality invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then f is a max flow. Pf.

By integrality invariant, when $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$.

Upon termination of Δ = 1 phase, there are no augmenting paths. •

Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats $1 + \lceil \log_2 C \rceil$ times. Pf. Initially $C \le \Delta < 2C$. Δ decreases by a factor of 2 each iteration. •

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then the value of the maximum flow is at most $v(f) + m \Delta$. \leftarrow proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase.

Let f be the flow at the end of the previous scaling phase.

 $L2 \Rightarrow v(f^*) \leq v(f) + m (2\Delta).$

Each augmentation in a Δ -phase increases v(f) by at least Δ .

Theorem. The scaling max-flow algorithm finds a max flow in $O(m \log C)$ augmentations. It can be implemented to run in $O(m^2 \log C)$ time. •

Capacity Scaling: Running Time

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then value of the maximum flow is at most $v(f) + m \Delta$.

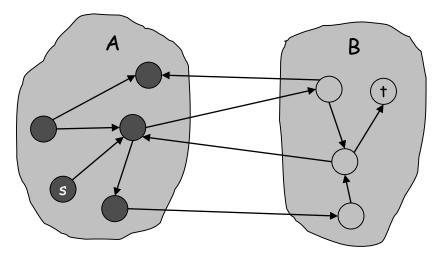
Pf. (almost identical to proof of max-flow min-cut theorem) We show that at the end of a Δ -phase, there exists a cut (A, B) such that cap $(A, B) \leq v(f) + m \Delta$. Choose A to be the set of nodes reachable from s in $G_f(\Delta)$. By definition of $A, s \in A$. By definition of f, $t \notin A$.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta$$

$$= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta$$

$$\geq cap(A, B) - m\Delta$$



original network