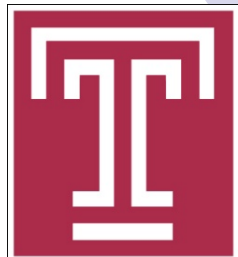


Mitigation of the Spectrum Sensing Data Falsifying Attack in Cognitive Radio Networks

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Road Map

1. Cooperative spectrum sensing
2. Related work
3. Majority voting and existing models
4. Weighted majority voting with confidence
5. Simulation results
6. Extension: two-level majority voting
7. Conclusion

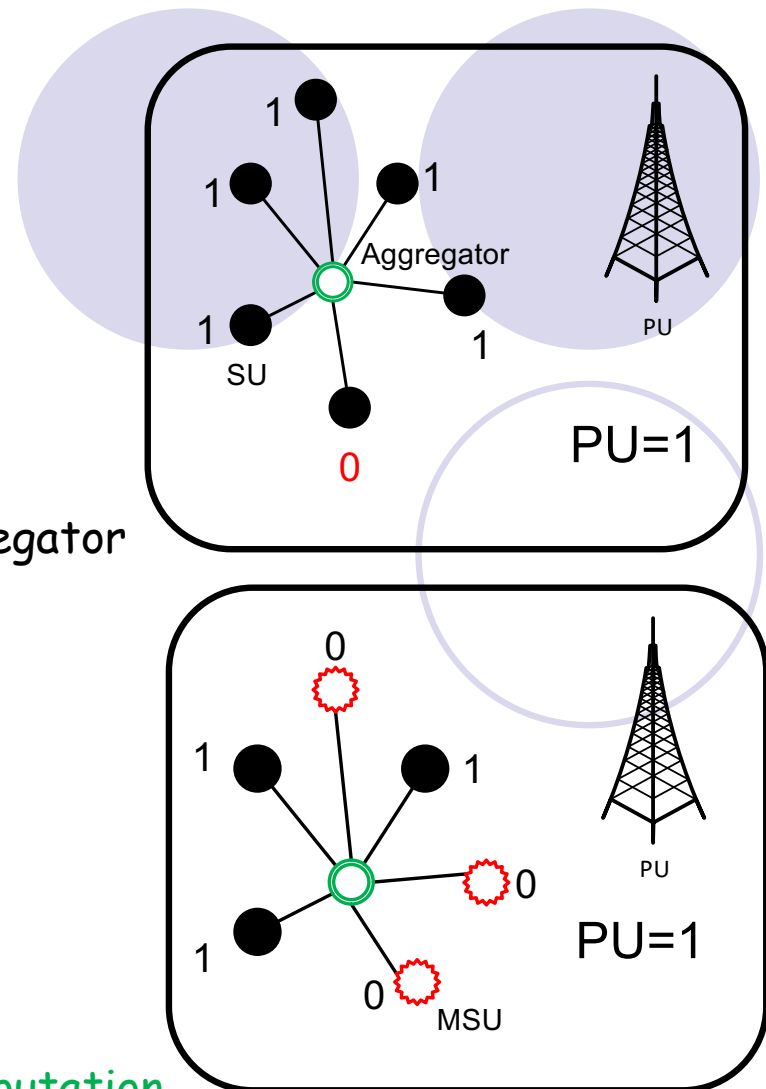


1. Cooperative Spectrum Sensing

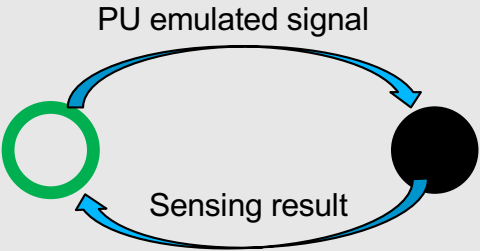
- Primary user (PU)
 - Licensed user, high priority
- Secondary user (SU)
 - Send sensing information to aggregator
- Malicious secondary user (MSU)
 - Send opposite sensing information to aggregator
- Aggregator
 - Does majority voting
 - Results are sent back to SUs and MSUs

SU's wrong sensing and *MSU's* result can *change aggregator's decision*

Solution: reduce weight of MSUs through reputation



2. Previous Work

MSU detection systems	Limitations
<p data-bbox="134 483 1234 678">Linear reputation-based system. SUs send raw sensing information to Aggregator. If a SU agrees with aggregator, reputation increases by "1" or decreases by "1".</p> <p data-bbox="172 704 1213 776">R. Chen, J. -. Park and K. Bian, "Robust Distributed Spectrum Sensing in Cognitive Radio Networks," IEEE INFOCOM 2008.</p>	<ul data-bbox="1325 483 1850 760" style="list-style-type: none">• Computation overhead is high for processing raw sensing information.• Linear reputation update mechanisms are not efficient enough.
<p data-bbox="134 938 961 987">Active transmission-based system.</p>  <p data-bbox="134 1312 1171 1419">T. Bansal, B. Chen, and P. Sinha, "Fastprobe: Malicious user detection in cognitive radio networks through active transmissions," in IEEE INFOCOM 2014.</p>	<ul data-bbox="1325 938 1829 1175" style="list-style-type: none">• PU emulated signals can be detected.• MSU will respond correctly to emulated signal.

3. Majority Voting and Existing Models

	SU1	SU2	SU3	SU4
Reputation	r1	r2	r3	r4
Sensing result	s1	s2	s3	s4

If $\sum s_i \hat{r}_i > 0.5$
Aggregator's decision=1
Else
Aggregator's decision=0

$$\hat{r}_i = \frac{r_i}{\sum r_i}$$

$\hat{r}_i =$ normalized reputation

Initial reputation=1

Aggregator
makes decision



Update reputation of SUs and MSUs
using Reputation Update Function (RUF)

Majority Voting and Existing Models

Linear RUF:

$$r_{new} = (\mu)r_{old} + (1 - \mu)x$$

μ = priority of previous reputation

If SU's result = aggregator's result

$$x = 1$$

Else

$$x = -1 \text{ (or 0, no decrease)}$$

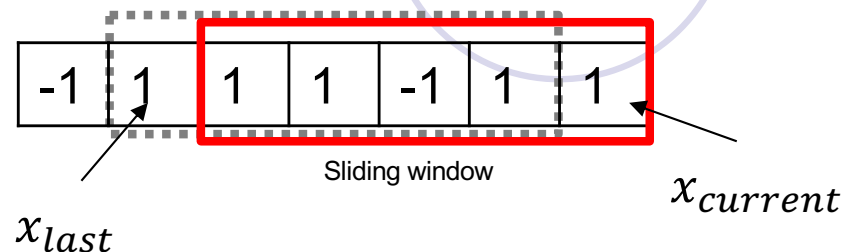
Multiplicative RUF*:

$$r_{new} = r_{old} \exp(\eta x)$$

η = learning rate: [0, 1]

Multiplicative RUF with sliding window:

$$r_{new} = r_{old} \exp(\eta x_{current} - \eta x_{last})$$

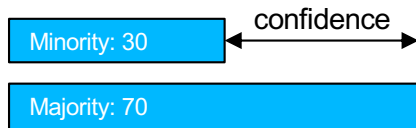


*S. Arora, E. Hazan, and S. Kale. "The multiplicative weights update method: a meta-algorithm and applications." Theory of Computing 8.1 (2012)

4. Weighted Majority Voting with Confidence

Adaptive Multiplicative RUF

- ρ_t = Normalized confidence
- $r_{new} = r_{old} \times \exp(x \eta \rho_t)$



$$\rho_t = \frac{|70 - 30|}{70 + 30} = 0.4$$

Ground truth	Time	0	100	200	300	400
	PU	1	0	0	1	1
Sensing result	SU1	1	1	0	1	1
	SU2	1	0	0	1	1
	SU3	1	1	0	1	0
	MSU1	1	1	1	0	0
	MSU2	0	0	0	0	0
Majority voting	A	1	1	0	1	0

False positive
False negative

$\eta = 0.01$

reputation	SU1	1	2.71	7.38	20.08	54.59
	SU2	1	2.71	1	2.71	7.38
	SU3	1	2.71	7.38	20.08	54.55
	MSU1	1	2.71	7.38	2.71	1
	MSU2	1	0.36	0.13	0.36	0.13

} High variance

A	1	1	0	1	0
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Without confidence

ρ	0.6	0.2	0.6	0.2	0.2
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reputation	SU1	1	1.82	2.22	4.05	4.95
	SU2	1	1.82	1.49	2.71	3.32
	SU3	1	1.82	2.22	4.05	4.95
	MSU1	1	1.82	2.22	1.22	1
	MSU2	1	0.54	0.44	0.81	0.67

} Low variance

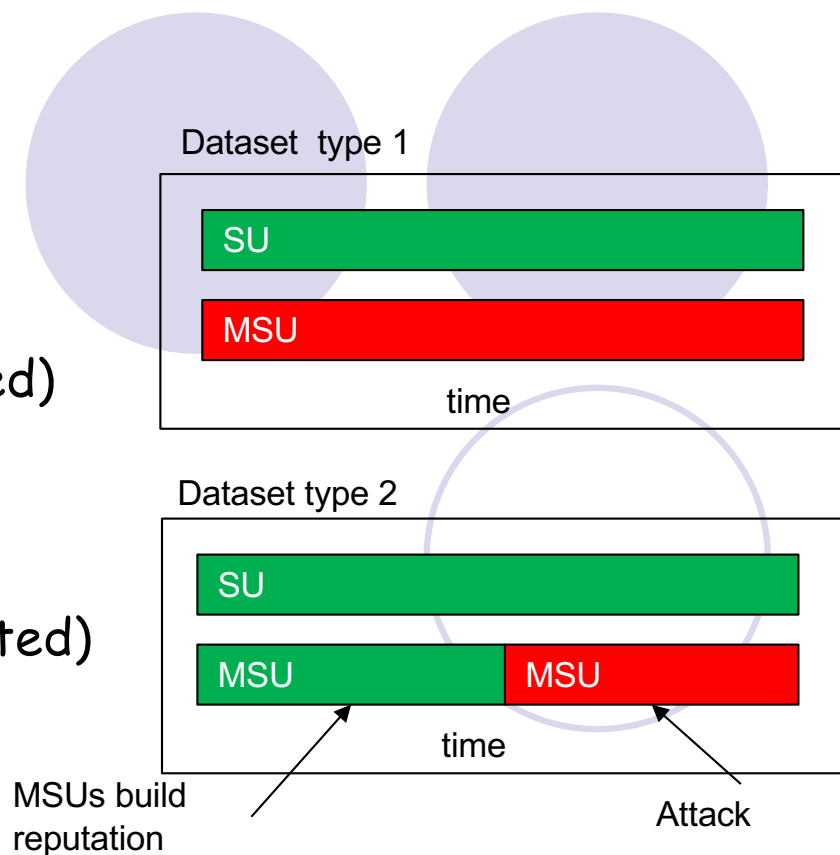
A	1	1	0	1	1
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With confidence

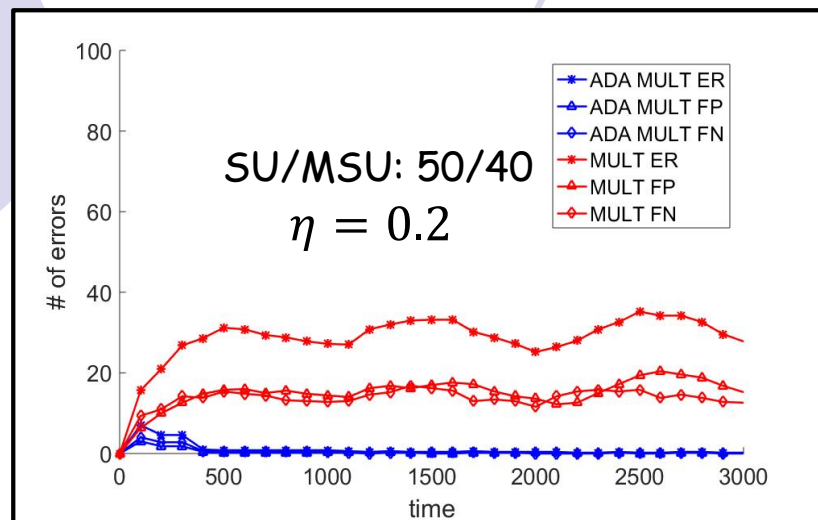
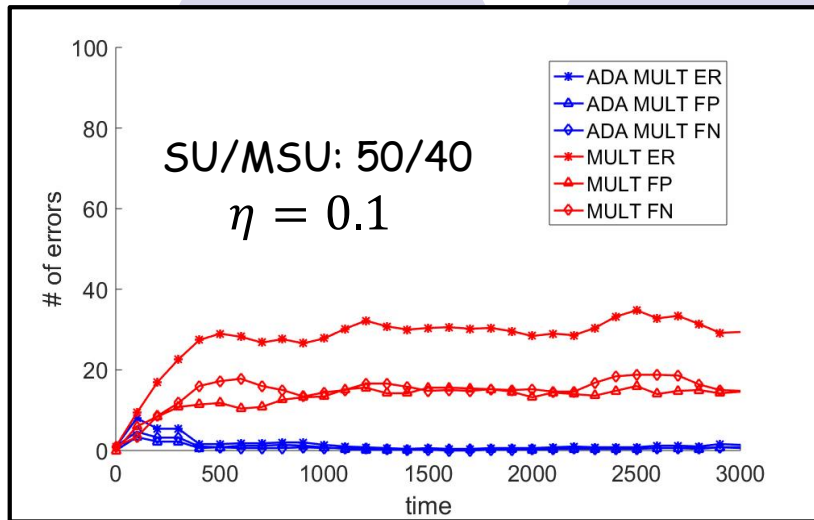
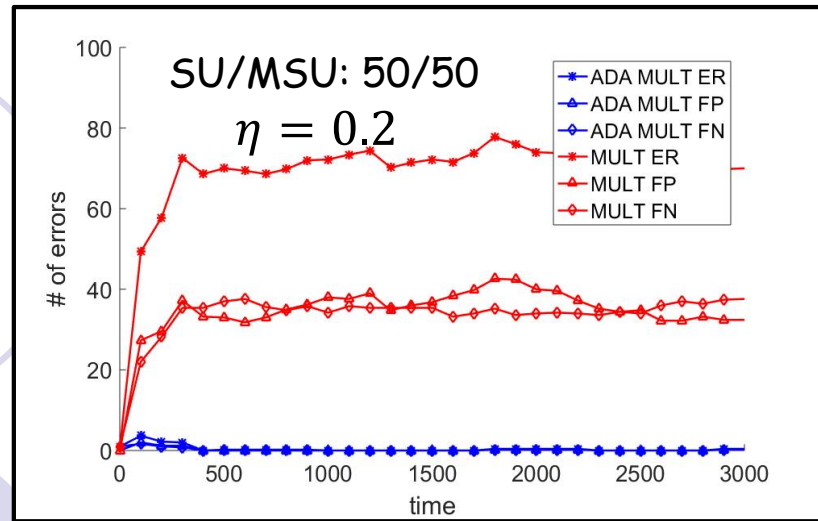
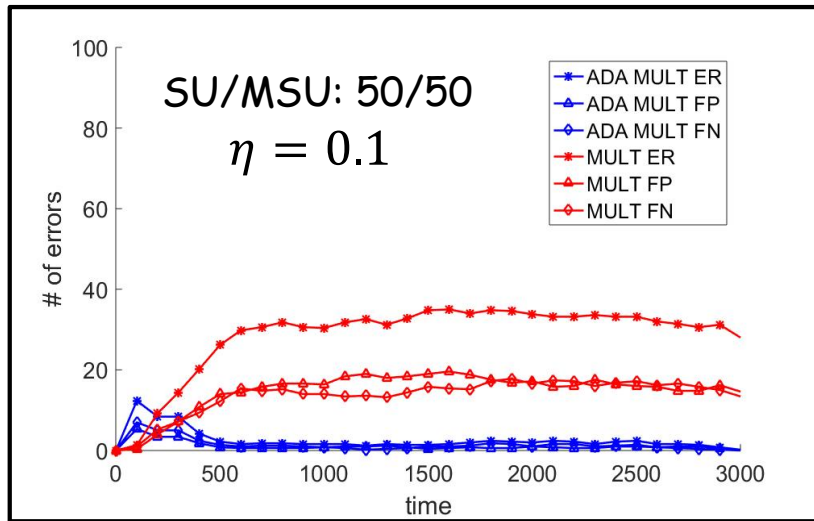
5. Simulation

Settings and datasets

- Number of SUs: 10-50
- SU error rate: 0-0.3 (randomly selected)
- Number of MSUs: 7-50
- MSU error rate: 0.7-1 (randomly selected)
- Initial reputation: 1
- Sensing records of 100,000 timeslots.



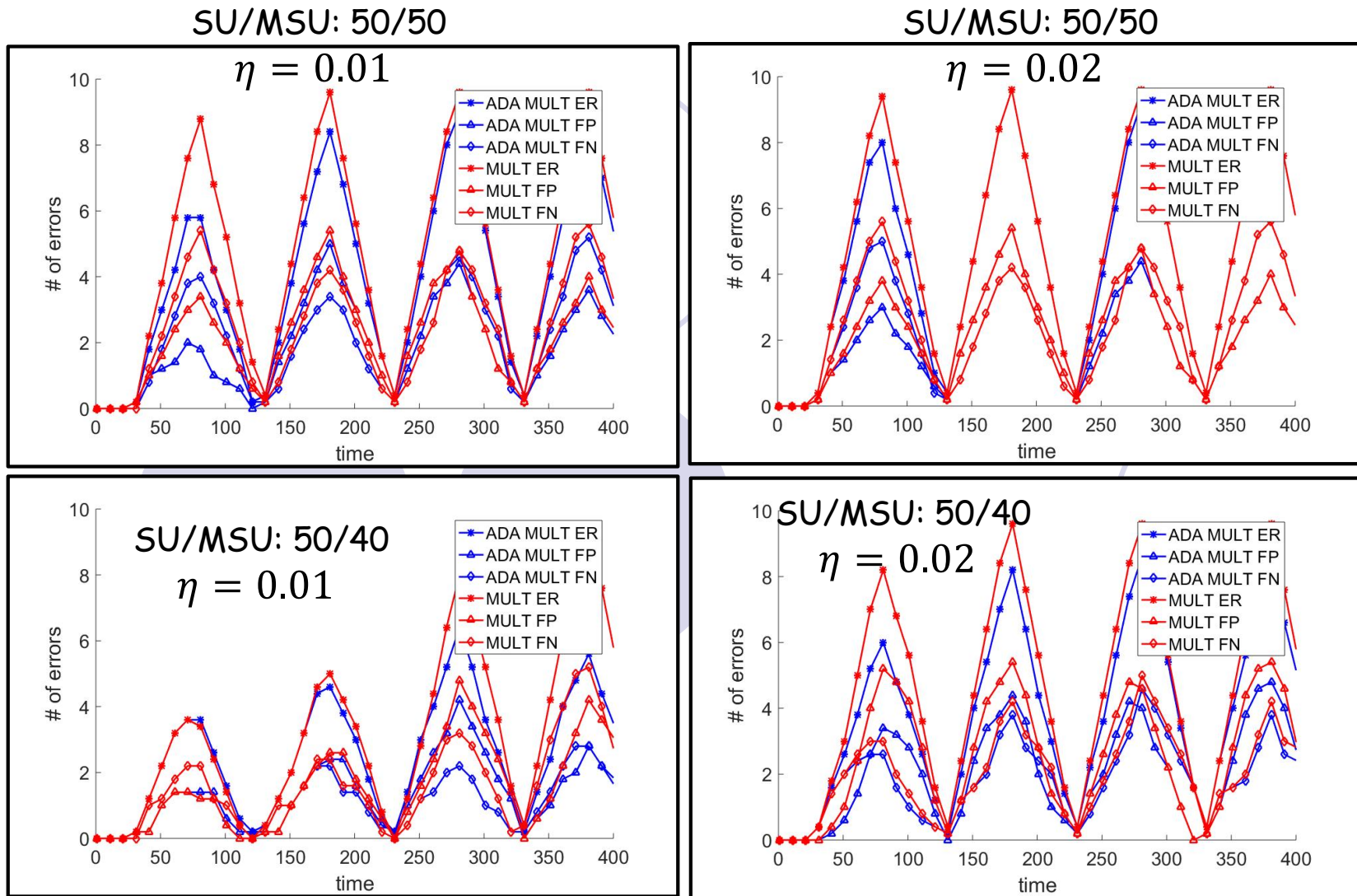
Multiplicative vs. Adaptive Multiplicative RUF



Dataset type 1 Used for simulation.

False positive (FP), False negative (FN), Error (ER), Adaptive multiplicative (ADA MULT), Multiplicative (MULT)

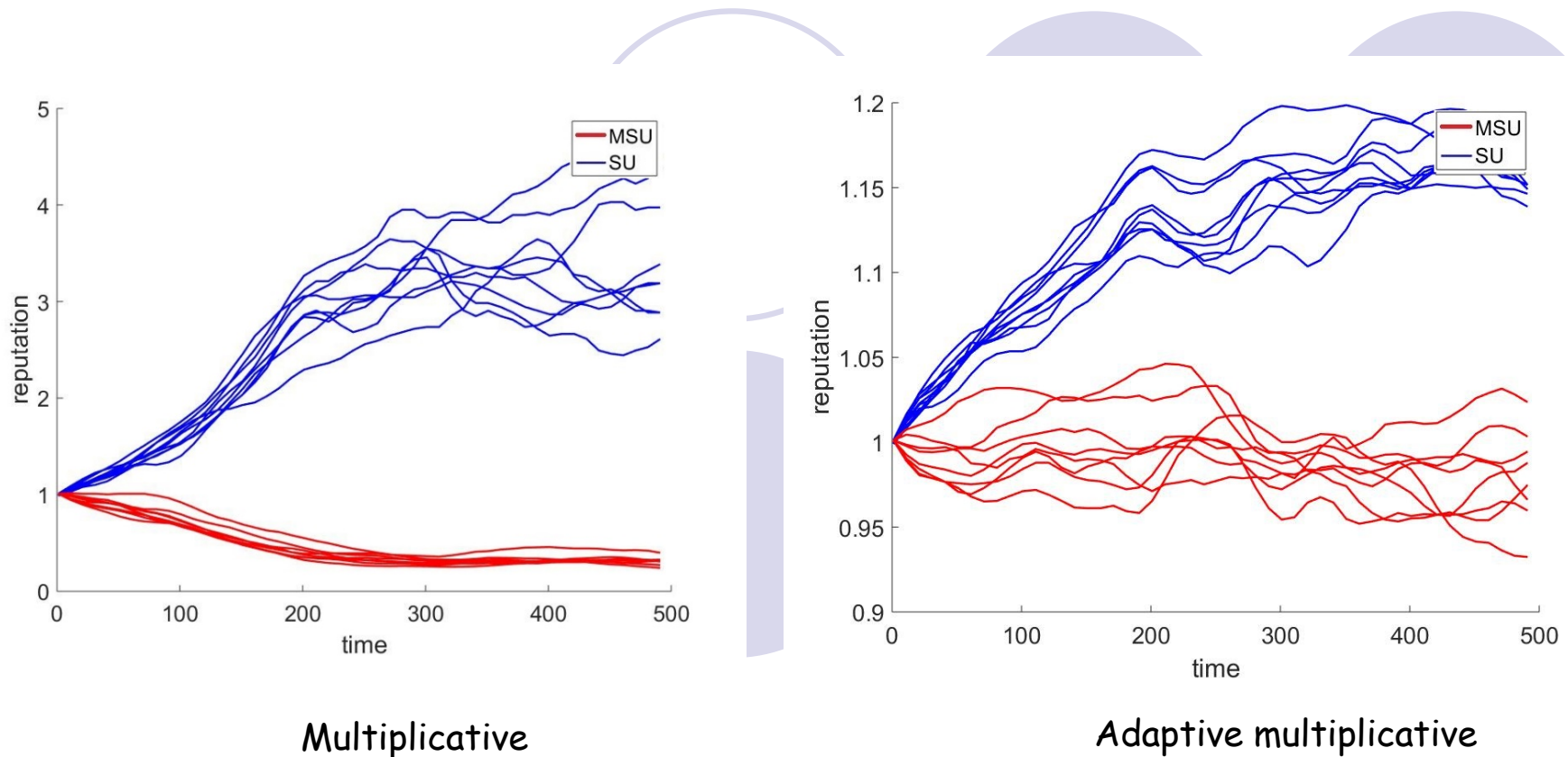
Multiplicative vs. Adaptive Multiplicative RUF



Dataset type 2 Used for simulation.

False positive (FP), False negative (FN), Error (ER), Adaptive multiplicative (ADA MULT), Multiplicative (MULT)

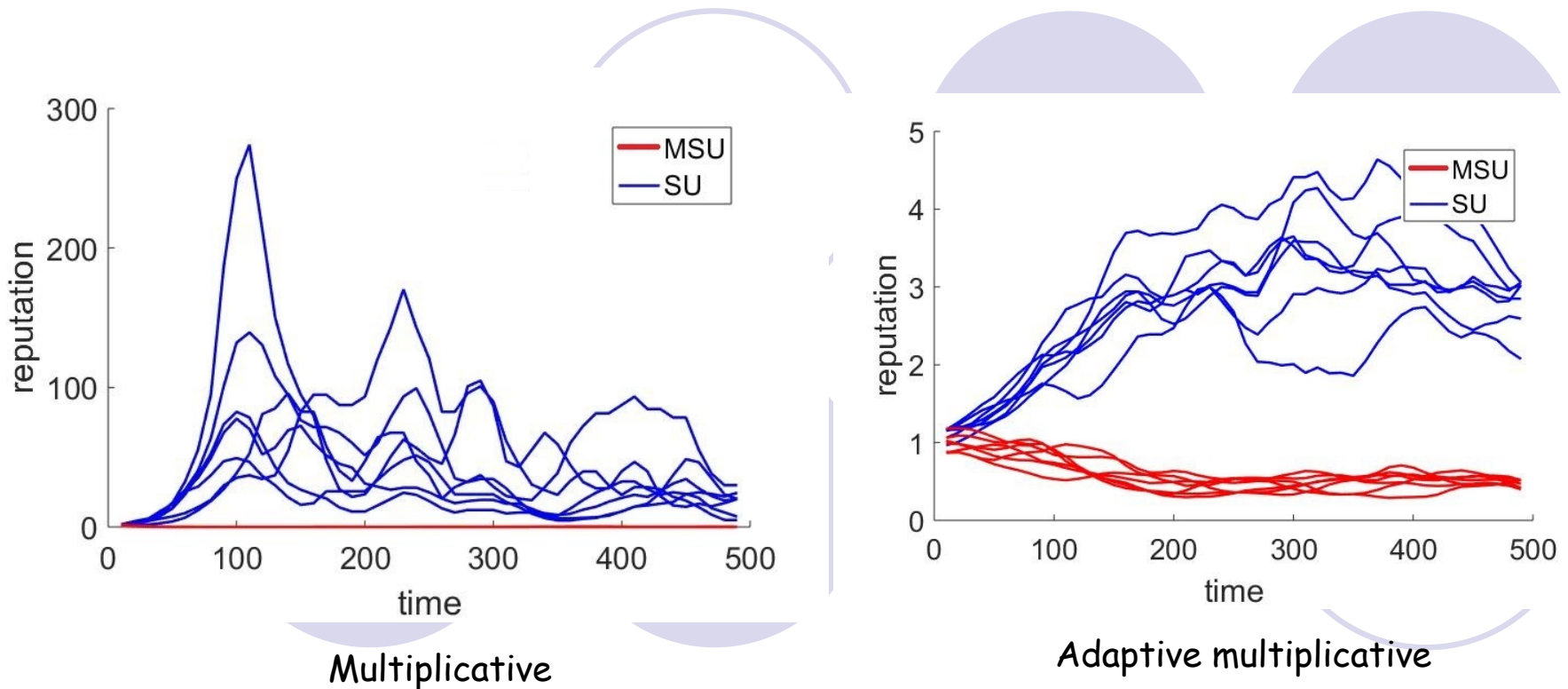
Multiplicative vs. Adaptive Multiplicative RUF



Dataset type 1 with $\eta = 0.01$

- Both work fine.
- High variation of reputation in multiplicative RUF may leads to more errors.

Multiplicative vs. Adaptive Multiplicative RUF



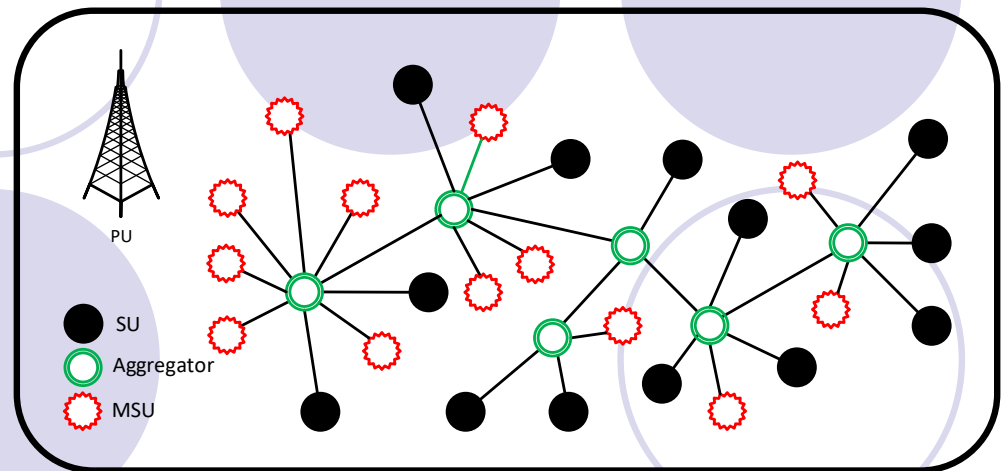
Dataset type 2 with $\eta = 0.01$

- High variation of reputation in multiplicative RUF leads to more errors.

6. Extension: Two-Level Majority Voting

A simple illustration

- 13 MSUs (clustered)
- 13 SUs
- 2 wrong aggregators
- 4 correct aggregators.



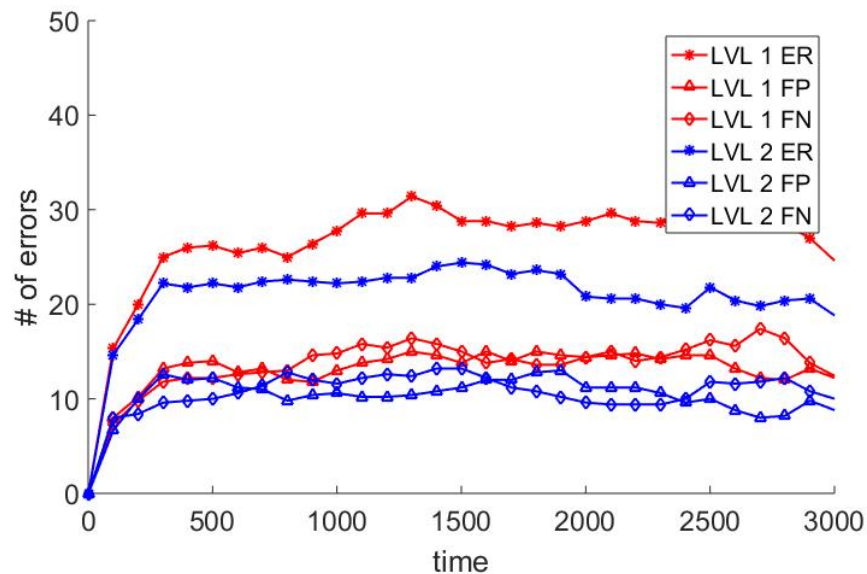
MSUs may win in one-level voting

MSUs cannot win in two-level voting

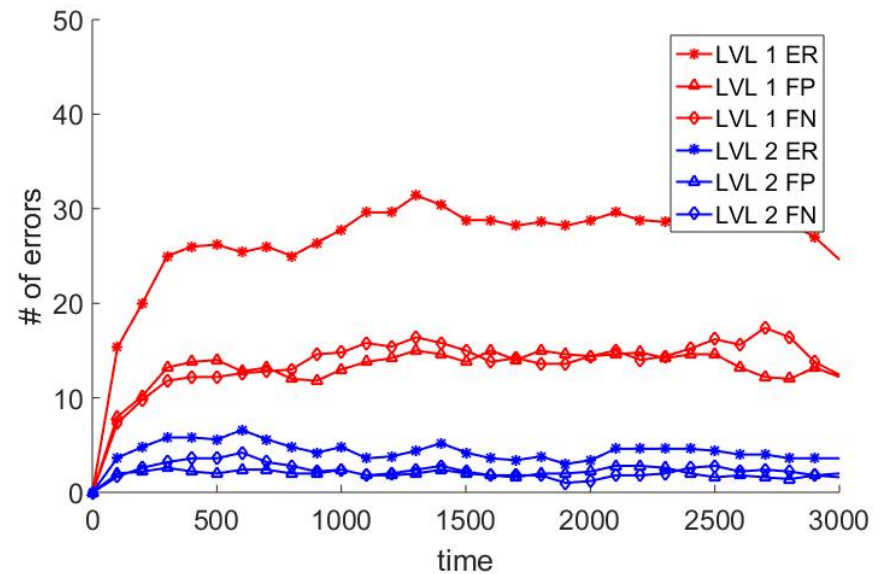
Connected dominating set based

distributed aggregator selection process

Two-Level vs. One-Level Voting



MSUs are sparse (uniform).



MSUs are clustered.

False positive (FP), False negative (FN), Error (ER), Level 1 (LVL 1), and Level 2 (LVL 2)

Dataset type 2 with $\eta = 0.01$

SU/MSU: 50/40

80% MSU: clustered

20% MSU and all SU: uniformly distributed

- Two-level voting works better when MSUs are clustered

7. Summary

- Adaptive multiplicative RUF using confidence
- Adaptive multiplicative RUF works better than other RUFs
- Two-level voting produces less errors than one-level voting

