Coverage and Workload Cost Balancing in Spatial Crowdsourcing

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Outline

- Introduction
- Model and problem
- Solution in 1-D scenario
- Solution in 2-D scenario
- Experiments
- Conclusion and future work





Background

From crowdsourcing to Spatial Crowdsourcing

- Crowdsourcing
 - Outsourcing at set of task to a set of workers
 - Human Intelligence Tasks (hard for computer, easy for human)



- Spatial Crowdsourcing
 - Crowdsourcing a set of spatial task to a set of workers
 - Traffic monitoring
 - climate measurement
 - ✤ Interesting point review





Background

Real applications:

- Spatial Crowdsourcing Service

- TaskRabbit (Home repair and refresh)
- Uber (Passenger/food delivery)
- WeGoLook (Inspection)
- FiELD Agent/ Gigwalk
- Information sharing*
 - Waze/Trapster (Traffic update)
 - WeatherSignal/OpenSignal
 - Local review (Google Local guide)





Related Works

Related works

- Worker trajectory planning
 - Plan worker's trajectory in crowdsourcing service
 - Maximize number of a worker's task
 - Maximize multiple workers' tasks (competition)
 - Crowdsourcing task can be time conflicted
- Worker recruitment problem*
 - Ensure crowdsourcing quality with worker's trajectory
 - Maximize the coverage area
 - Minimize the overall recruitment cost





Network Model

Our model

- Information sharing*
- Worker recruitment problem*

Sharing economy!

 You will not be bothered by the crowdsourcing platform, but you and others can benefit from this.





Network Model

Network Model

- Multiple Workers, $\{w_1, w_2, ..., w_n\}$
 - known trajectory, t_i, and recruiting cost, c_i, for visiting a crowdsourcing location.
- Many crowdsourcing locations, $\{I_1, I_2, ..., I_m\}$
 - Pay worker c_i when w_i passes this location
- Grid network
 - Fit real road networks









Problem Formulation

Coverage and Balanced Crowdsourcing Recruiting (CBCR) problem

- Coverage requirement
 - All the crowdsourcing locations should be covered/visited
- Balancing crowdsourcing location cost
 - The maximum cost of crowdsourcing location should be minimized

$$\min \qquad \max_{i} \sum_{l_i \in t_j} c_j x_j$$
s.t.
$$\sum_{l_i \in t_j} x_j \ge 1, \quad \forall l_i \qquad x_j \in \{0, 1\},$$

• NP-hard in general scenario



Application scenario People/vehicles in highway, main street



illustration



worker	Covered locations	cost
w1	1, 2	1
w2	12, 13, 14	1.5
w3	13, 14	3
w4	14	2



Min-max Greedy algorithm (MG)

- While the network is not covered, we select the worker who can minimize the maximum cost among all the crowdsourcing locations in the network.



-Analysis: the error can be accumulated/ nonsubmoduar



Coverage-Only Greedy algorithm (CO)
 While the network is not covered, we select the worker who can increase coverage most from one side to the other side (e.g., from left to right).



Theorem: The CO algorithm has a $2max|c_i/c_j|$, for all i,j, approximation ratio in the 1-D scenario.





- PTAS in CO algorithm
 - Analysis: worker with high cost can be selected
 - Idea: Set work with high cost a low priority
 - Algorithm implementation
 - *Set a threshold, ϵ , separate workers into two sets in terms of cost
 - costly workers and cheap workers
 - Apply CO algorithm in cheap workers
 - If it successes, reduce the threshold
 - If it fails, increase the threshold

Binary search to find the smallest threshold

Theorem: The CO algorithm has a 2+ ϵ approximation ratio in the 1-D scenario.





Dynamic programming (Optimal sub-structure)

 Sort all trajectories based on end points from left to right
 The optimal solution for crowdsourcing location i with worker w_j as the last worker.

$$d[i,j] = \begin{cases} 0 & \text{i} = 0\\ \min_{i' < i, j' \le j} \max\{d[i',j'], c_{j'} + c_j\} & \text{Otherwise} \end{cases}$$



location worker	I	2	3	4
Ι	Ι			
2	Ι	2.5		
3		2.5	3	
4		2.5	3	3.5



Challenge

- The overlapping relationship becomes complex
 - 1-D continuous overlap
 - 2-D discrete overlap



 Optimal substructure does not exist and dynamic programming does not work

Center for Networked Computing



Idea

- Extend the proposed algorithms in 1-D scenario
 - Min-max algorithm is still the same.
 - Coverage-only algorithm can be used line-by-line.

Randomized Rounding Algorithm

- Relax the original problem into the linear problem $\min \theta$

s.t.
$$\sum_{l_i \in t_j} c_j x_j \le \theta$$
, $\sum_{l_i \in t_j} x_i \ge 1$, $\forall i, j$ $x_i \in [0, 1]$

 Use the expected value as the selection probability and randomly select workers.

Theorem: The randomized rounding algorithm has a O(log(n)/loglog(n)) expected approximation ratio





Experiment Evaluation

Experiment Setting

- Trajectory Trace Information
 - EPFL: 500 taxies in San Francisco, USA
 - Seattle: 236 buses in Seattle, USA
- Trajectory Trace Information
 - Uniform/exponential distribution with 5 cost
- Experimental area: downtown









Algorithm comparison

- Four algorithms in 1-D:
 - Min-Max greedy (MG)
 - Coverage-Only (CO)
 - PTAS (PT)
 - Dynamic programming (DP)
- Four algorithms in 2-D:
 - Min-Max greedy (MG): the same
 - Coverage-Only (CO): row-by-row /
 - PTAS (PT)
 - Dynamic programming (DP): do not apply
 - Randomized Rounding (RD)



Performance Result

1D Different number of crowdsourcing locations





Performance Result

1DDifferent cost distribution

- Uniform/Exponential





Performance Result

2DDifferent number of crowdsourcing locations







- We investigate a worker recruitment problem in spatial crowdsourcing scenario, where coverage and balance location cost are jointly considered.
- A series of algorithm is proposed in 1-D scenario to trade-off the performance and computation complexity.
 - Coverage-Only algorithm
 - PTAS algorithm
 - Dynamic programming algorithm
- A randomized rounding scheme is proposed in a general scenario.





Future works

- Efficient deterministic algorithm in 2-D scenario
- Weighted coverage and heterogeneous cost
- Trade-off between detour and benefit
- System implementation (if possible)





Thank you and Question

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