

# Transfer Learning in Wireless Channel Prediction

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## Introduction

### Cellular systems

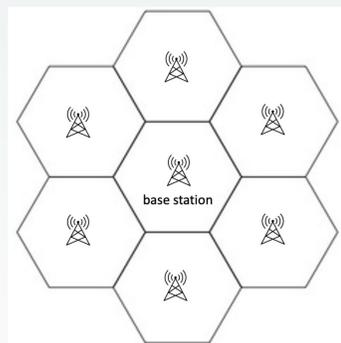
- Transmit data via radiofrequency (RF) signals
- Provide RF channels for data transmission services
- Four major components
  1. Cellular towers and antennas
  2. Public switched telephone network (PTSN)
  3. Mobile telephone switching office (MTSO)
  4. Mobile subscriber units (MSU)

### Channel switching

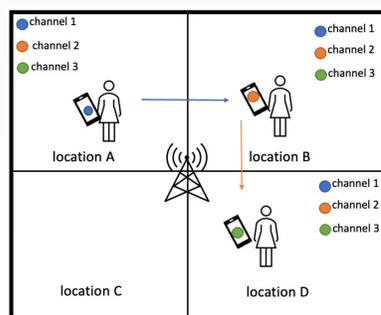
- Switch RF channels based on
  1. User location
  2. Signal strength
  3. Availability

### Transfer learning

- Transfers knowledge from one domain to another
- Subfield of machine learning
- Applications
  1. Computer vision (CV)
  2. Natural language processing (NLP)



Cellular systems.



RF channel switches based on user location.

## Problem Formulation

### RF channel switching is

1. Time-consuming
2. Resource-intensive

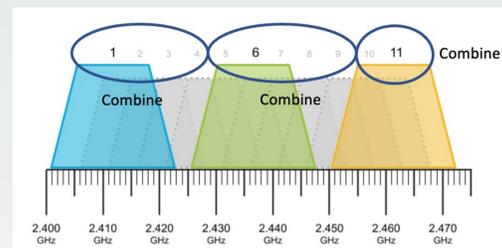
### Transfer learning is

1. Less time-consuming to train models
2. Less data-dependent to train models

Goal: Minimize channel switching

### RF channels overlap in 2.4 GHz band

- Combine overlapping channels



RF channel are combined in dataset.

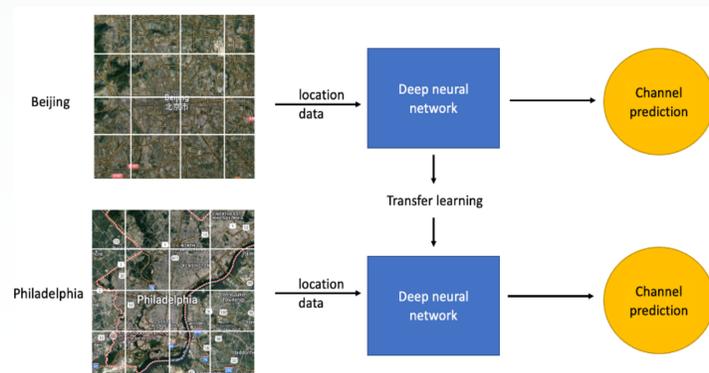
## Instance-based transfer learning

### Homogeneous transfer learning

- Source and target domains have similar tasks

### Instance-based transfer learning

- Corrects marginal and distribution differences
- Assign weights to the loss function of source domain
- Target domain uses the assigned weights



The knowledge gained from Beijing (City A) can transfer to Philadelphia (City B).

### Weighting strategy

- $\mathbb{E}_{(x,y) \sim P^T}[\mathcal{L}(x,y;f)] = \mathbb{E}_{(x,y) \sim P^S} \left[ \frac{P^T(x,y)}{P^S(x,y)} \mathcal{L}(x,y;f) \right]$
- $\mathbb{E}_{(x,y)}$  is the expected risk
- $x$  is the pattern in the domain
- $y$  is the label in the domain
- $\mathcal{L}(x,y;f)$  is the loss function that depends on the parameter  $f$
- $P^T(x)$  is source domain,  $P^S(x)$  is target
- $\frac{P^T(x,y)}{P^S(x,y)}$ : Instances are drawn from source, and generalized to target
- Generalized instances are now the weighting parameters  $\rightarrow \beta(x, y)$
- Estimate the weighting parameter
- $\min_f \frac{1}{n} \sum_{i=1}^n \beta_i \mathcal{L}(f(x_i^s), y_i^s) + \Omega(f)$
- $\beta_i$  is the weighting parameter
- $n$  is the number of instances
- $\Omega(f)$  is the regularizer of the re-weighted risk

## Proposed Simulation Techniques

### Two cities examined:

- City A (Beijing) and City B (Philadelphia)
- City A -----transfer knowledge----> City B

### Basic model for simulations

- 7-layer DNN for model training
- Latitude + Longitude ~ Channel
- Predict occupied channels of location

### Baseline and Upper bound

- Baseline: averaging 100 accuracy of City A -transfer -> City B results
- Upper bound: result of training City B model

### Varying training data ratio

1. Train certain % of A data
2. Use the same model, train certain % of B data
3. Different combinations of % A and B data

### Fine-tune initial learning rates

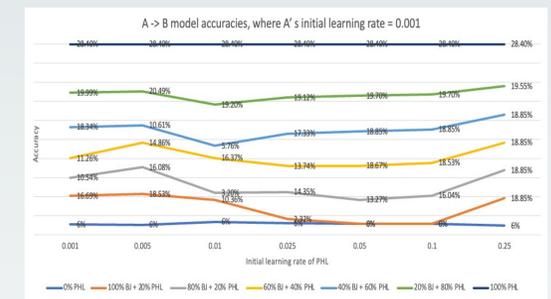
1. Assign a set of learning rate (LR) for City A
2. For each LR of City A, a set of LR assigns to City B

3. For each pair of LR ( $LR_A, LR_B$ ), train model with different combinations of Cities A and B data

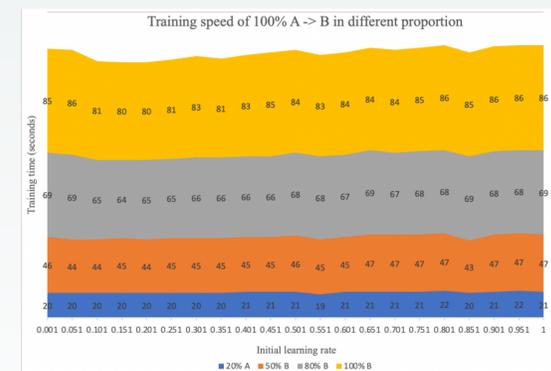
### Training time vs. accuracy

1. Assign a set of LR for training
2. Cities A and B use the same LR
3. Train City A --> B in different %
4. Record training time and accuracy

## Evaluation



- As % B increases, accuracy increases.



- Training speed of A -> B.
- Uses less training time while maintaining some level of accuracy.

## Conclusion

- Transfer learning is feasible in predicting the used channels in each location
  - Propose simulation techniques
  - Fine tune DNN model and adjust data ratio to generate test results
  - Experiments verify the performance
  - Useful when time and data are scarce