A Combinatorial Multi-Armed Bandit Approach for Stochastic Facility Allocation Problem

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- Problem Formulation
- Solution of the Problem
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Introduction

• Background of Facility Allocation:

- Strategic placement of resources in various fields: urban planning, telecommunications, computing infrastructure.
- Focus on optimizing spatial resources in dynamic, uncertain conditions.

• Problem Complexity:

- Decision-making is iterative, aiming to maximize total reward over multiple rounds.
- Challenges in environments with variable demands, like emergency services and telecommunications.
- Combinatorial nature: multiple facilities are decided upon simultaneously.

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Problem Formulation

- Model Setup:
 - **Grid Layout**: 1× 1 square divided into *N* cells (perfect square).
 - **Population Density**: Each cell *i* has an unknown fixed density *D*(*i*).
- Facility Allocation:
 - **Round-by-Round Decision**: Allocate *K* facilities at cell centers per round, represented as $F(t) = \{f_1(t), ..., f_K(t)\}$.
 - **Unique Positioning**: No two facilities share the same location in the same round.
- Voronoi Partitioning:
 - Determines which facility point each cell is closest to, using either Manhattan or Euclidean distance.
 - Cells are assigned to the nearest facility, breaking ties randomly.

Problem Formulation

- Attraction Probability:
 - Probability $p_{i,j}(t)$ of attracting an individual from cell *i* to facility *j* inversely proportional to their distance.
 - Modeled as: $\frac{\alpha}{d(f_j(t),i)+1}$, where α is a tunable factor and d is the chosen distance metric.
- Expected Population Attraction:
 - Each round models population attraction as a binomial random variable:

 $X_i(t) \sim Binomial(D(i), p_{i,j}(t)).$

- Expected attracted population from cell *i* to facility $j: E[X_i(t)] = \sum_{j \le K} D(i)p_{i,j}(t)$.
- Regret Minimization Objective:
 - **Regret Definition**: Difference between optimal and actual attracted population over rounds.
 - **Optimization Goal**: Minimize cumulative regret by selecting F(t) to maximize total expected population attraction.

Problem Formulation



Figure 1: An illustration showing the effect of the choice of distance metric on the Voronoi partition $V_j(t) \quad \forall j \leq K$. The background color represents the value of the underlying population density of the cells D(i): (a) Euclidean distance metric; (b) Manhattan distance metric.

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Solution of the Problem

Algorithm 1 Geometric-UCB for facility allocation

Input: $D(i) \forall i \leq N, K$, distance metric.

Output: $F(t) \quad \forall t = 1, 2, ..., T.$

Initialization: $X_i(0) \leftarrow 0 \forall i \leq N, \hat{\mu}(\mathbf{F}, t) \leftarrow 0 \text{ and } N_{\mathbf{F}}(t) \leftarrow 0 \forall \mathbf{F}$

1: for t = 1, 2, ..., T do

- 2: for all possible allocations F do
- 3: Evaluate $UCB(\mathbf{F}, t)$ from Equation 4.
- 4: Choose F(t) based on Equation 5.
- 5: Perform the Voronoi partition based on F(t) and the chosen distance metric to get $V_j(t)$ for all $j \le K$.
- 6: Observe $X_i(t) \quad \forall i \leq N$ and update $\hat{\mu}(\mathbf{F}, t)$ and $N_{\mathbf{F}}(t) \quad \forall \mathbf{F}$ based on Equations 6-7.

7: return F(1), F(2), ..., F(T).

$$UCB(\mathbf{F}, t) = \hat{\mu}(\mathbf{F}, t) + \sqrt{2\log t/N_{\mathbf{F}}(t)}, \tag{4}$$

$$\mathbf{F}(t) = \arg\max_{\mathbf{F}} \left(\hat{\mu}(\mathbf{F}, t) + \sqrt{2\log t / N_{\mathbf{F}}(t)} \right).$$
(5)

$$\hat{\mu}(\mathbf{F}, t+1) = \frac{N_{\mathbf{F}}(t)\hat{\mu}(\mathbf{F}, t) + \sum_{j=1}^{K} \sum_{i \in V_j(t)} X_i(t)}{N_{\mathbf{F}}(t) + 1}.$$
 (6)

$$N_{\rm F}(t+1) = \begin{cases} N_{\rm F}(t) + 1 & \text{if } {\rm F}(t) = {\rm F} \\ N_{\rm F}(t) & \text{otherwise} \end{cases}$$
(7)

THEOREM 5.1. Algorithm 1 guarantees a regret bound of:

$$R(T) \le 2\sqrt{2N\log T} \left(1 + 1/\sqrt{N}\right).$$

Solution of the Problem

• Algorithm Choice:

- Utilizes a Combinatorial Upper Confidence Bound (C-UCB) algorithm.
- Balances exploration (gaining new information) and exploitation (using known high-reward locations).

• Algorithm Overview:

- Expected Attraction: Computes expected total population attraction for different facility sets, F(t).
- **UCB Formula**: Incorporates both past data and an exploration bonus to guide allocation decisions.

• Algorithm Execution:

- **Initialization**: Sets initial conditions for all variables and parameters.
- **Iteration Process**: Evaluates and chooses facility sets based on their upper confidence bounds across all rounds.
- **Voronoi Partitioning**: Performed each round to determine the influence area of each facility based on chosen distance metric.
- **Observation and Update**: Records results from the current allocation to refine future decisions.

Solution of the Problem

• Key Features of Geometric-UCB:

- Uses real-time data to dynamically adjust decisions.
- Aims to maximize total attraction over time, minimizing regret.
- Suitable for scenarios where the number of facilities (*K*) is small, making complex computations tractable.

• Computational Complexity:

• **Time Complexity**: Dominated by evaluating all potential allocations $(O(T \times N^K))$ and computing Voronoi partitions each round $(O(T \times K^2))$.

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• Experimental Settings Overview:

- Facility Numbers: K = 3 or 4 to manage computational feasibility.
- **Probability Parameter**: *α* varied from 0.1 to 1.0 to test different attraction levels.
- **Distance Metrics**: Both Manhattan and Euclidean used to examine adaptability.

• Data Used for Simulation:

- **Real-World Traces**: Population density data from the United States, discretized into 36 or 49 cell grids.
- **Synthesized Data**: Generated datasets with population densities drawn from a normal distribution to test across varied scenarios.

- Algorithm Comparison:
 - **Epsilon-Greedy Algorithm**: Examines balance between exploration and exploitation, with $\epsilon = 0.25$.
 - **Thompson Sampling**: Assesses performance against a probabilistic method that uses Bayesian inference for decision-making.
 - **Random Selection**: Provides a baseline by randomly choosing facility locations, ignoring prior data.

• Goals of Comparative Evaluation:

- Test the Geometric-UCB's efficiency against established algorithms.
- Identify strengths and potential areas for improvement in different settings.
- Validate robustness and adaptability of Geometric-UCB under varied experimental conditions.



Figure 3: Total regret value for different algorithms under synthesized data with different α values. $\mu_D = 5000, \sigma_D = 100$.



Figure 4: Regret value for different algorithms under synthesized data with different N values. $\mu_D = 5000, \sigma_D = 100$.



Figure 5: Regret value for different algorithms under realworld traces with different *K* values.

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Future Work

• Expanding Dimensions:

- Explore the applicability of the Geometric-UCB algorithm in higherdimensional spaces.
- Test the scalability and computational feasibility as dimensions increase.

• New Performance Measures:

- Investigate other metrics beyond regret to assess the algorithm's effectiveness.
- Consider factors like computational efficiency, convergence speed, and robustness under varying conditions.

• Refinement of Probability Parameter (*α*):

- Develop adaptive strategies for tuning α dynamically based on observed attraction levels.
- Enhance the algorithm's responsiveness to changes in population density and attraction patterns.

Conclusion

• Key Contributions:

- Introduced a novel Geometric-UCB algorithm tailored for the stochastic facility allocation problem.
- First application of CMAB techniques in 2-dimensional spaces with uncertain population distributions.

• Algorithm Advantages:

- Efficiently balances exploration and exploitation to maximize total population attraction.
- Demonstrated adaptability with both Manhattan and Euclidean distances in facility allocation.

• Validation through Simulations:

- Tested on both real-world data and synthesized datasets to verify effectiveness and efficiency.
- Outperformed traditional algorithms like Epsilon-Greedy and Thompson Sampling in various setups.

Thank you!

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